



DS/RS Installation & Wiring

Contents

| | |
|--|----|
| 1. Installing the ASB and RS Rack | 3 |
| 2. Wiring the Data Handler Board | 11 |
| 3. Wiring the T/C-Analog Board | 16 |
| 4. Wiring the High Speed Analog (Parison, EZ PRO, Injection) Board | 20 |
| 4.1 Introduction | 20 |
| 4.2 Analog Input/Output Wiring Guidelines | 20 |
| 4.2.1 Injection Control Ram Position and Ram Pressure Inputs | 20 |
| 4.2.2 EZ PRO Version 13.08 Changes Relating to Switch 3 | 21 |
| 4.3 Wiring DC Inputs & Outputs | 23 |
| 4.4 Specifications | 24 |
| 5. Using the 4-Slot Carrier Board | 36 |
| 5.1 Introduction | 36 |
| 5.2 Wiring the Digital I/O Boards | 38 |
| 5.2.1 Introduction | 38 |
| 5.2.2 Specifications | 38 |
| 5.3 Wiring the 2 Channel Analog Input Board | 42 |
| 5.3.1 Introduction | 42 |
| 5.3.2 Specifications | 42 |
| 5.4 Wiring the MACO-NET Communications Board | 45 |
| 5.4.1 Introduction | 45 |
| 5.5 Wiring the Encoder Board | 47 |
| 5.5.1 Introduction | 47 |
| 5.5.2 Specifications | 47 |
| 6. Wiring the 32 In/32 Out or 24 In/24 Out Digital I/O Boards | 50 |
| 6.1 Introduction | 50 |
| 6.2 Specifications | 50 |

Figures

| | |
|--|----|
| Figure 1. ASB Mounting (front view) | 4 |
| Figure 2. ASB Mounting (side view) | 5 |
| Figure 3. ASB Slot Numbering | 6 |
| Figure 4. RS and SRS Rack Mounting | 7 |
| Figure 5. RS Rack Slot Numbering | 8 |
| Figure 6. Processor and Communication Options | 9 |
| Figure 7. ASB Front Door Label | 10 |
| Figure 8. ASB Front Clear Overlay | 10 |
| Figure 9.1 Data Handler Card A-60134-xx1 | 12 |
| Figure 9.2 Data Handler Card A-60149 with Processor | 13 |
| Figure 9.3 Data Handler Card A-60149 with Anybus Card | 14 |
| Figure 9.4 Two Slot Carrier/Sequence Board (Rack Systems only) | 15 |
| Figure 10. Installing Resistors for Current Inputs | 17 |
| Figure 11. T/C-Analog Card A-60133-xx1 | 18 |
| Figure 12. Wiring Thermocouple Inputs using the T/C-Analog Card | 19 |
| Figure 13. Wiring Analog Inputs using the T/C-Analog Card | 19 |
| Figure 14. High Speed Analog (Parison, EZ PRO, Injection) Card A-60136-xx0 | 25 |

| | | |
|------------|--|----|
| Figure 15. | Wiring High Speed Analog Card DC Inputs | 26 |
| Figure 16. | Wiring High Speed Analog Card DC Outputs | 26 |
| Figure 17. | Wiring High Speed Analog Card Analog Inputs | 27 |
| Figure 18. | Wiring High Speed Analog Card Analog Outputs | 27 |
| Figure 19. | High Speed Analog Sensor Wiring | 28 |
| Figure 20. | High Speed Analog Card Pressure Transducer Wiring | 29 |
| Figure 21. | High Speed Analog Card DC Input and Output Wiring | 29 |
| Figure 22. | One-Head Time-Based Machine with B-C Servo Amp | 30 |
| Figure 23. | Two-Head Time-Based Machine with B-C Servo Amp | 31 |
| Figure 24. | Two-Head Position-Based Machine with B-C Servo Amp | 32 |
| Figure 25. | Two-Head Position-Based Machine with Pushout and B-C Servo Amp | 33 |
| Figure 26. | Accumulator Machine (Velocity Control) with B-C Servo Amp | 34 |
| Figure 27. | Two-Head Position-Based Machine with Moog Servo Amp | 35 |
| Figure 28. | Four Slot Carrier Board A-60142-xx0 | 37 |
| Figure 29. | 8 Input/Output Digital I/O Card A-60138-xx0 | 39 |
| Figure 30. | 8 Input/Output Digital I/O Wiring | 40 |
| Figure 31. | 8 Input/Output Sample Wiring | 41 |
| Figure 32. | Two Channel Analog Input Card A-60148 | 43 |
| Figure 33. | Wiring for External Cal Resistor | 44 |
| Figure 34. | Wiring for Internal Cal Resistor | 44 |
| Figure 35. | MACO-NET Card A-60187 | 46 |
| Figure 36. | Encoder Card A-60191 | 48 |
| Figure 37. | Wiring the Encoder Card | 49 |
| Figure 38. | 32 In/32 Out or 24 In/24 Out A-60150-x | 51 |
| Figure 39. | 32 In/32 Out or 24 In/24 Out Digital I/O Wiring | 52 |
| Figure 40. | 32 In/32 Out or 24 In/24 Out Sample Wiring | 53 |
| Figure 41. | Sample System Wiring | 54 |
| Figure 42. | Adding or Replacing Boards | 55 |
| Figure 43. | Disassembling the Data Handler Block | 57 |

Tables

| | | |
|----------|---|----|
| Table 1. | Switch Settings for Modbus and Modbus Plus Addressing | 11 |
|----------|---|----|

1. Installing the ASB and RS Rack

The ASB and the RS Rack are rated at 24 Vdc (20 to 30 Vdc), 1.5 Amps maximum current at 24 Vdc (excluding all I/O); operating temperature of 0 to 55°C (32 to 131°F); storage temperature of -40 to 85°C (-40 to 185°F); 0 to 95% rh, non-condensing @ 55°C (131°F).

These controllers are Installation Category 3 and Pollution Degree 2 devices. They are intended for panel mounting only.

Where external power supplies are required, a CE recognized supply must be used. Test results on CE power supplies have shown that they may emit noise above 30 MHz. Install a ferrite bead suitable for power cord use at the output terminals of the supply.

“Bonding” requires the removal of all non-conductive plating or coatings between the surfaces to be bonded (as well as the application of pressure).

Include a switch or circuit breaker in the installation. It must be placed in close proximity to the equipment, within easy reach of the operator and must be marked as the disconnecting device for the equipment.

A.1



CAUTION:

Risk of Electric Shock - More than one disconnect switch may be required to deenergize the equipment before servicing.

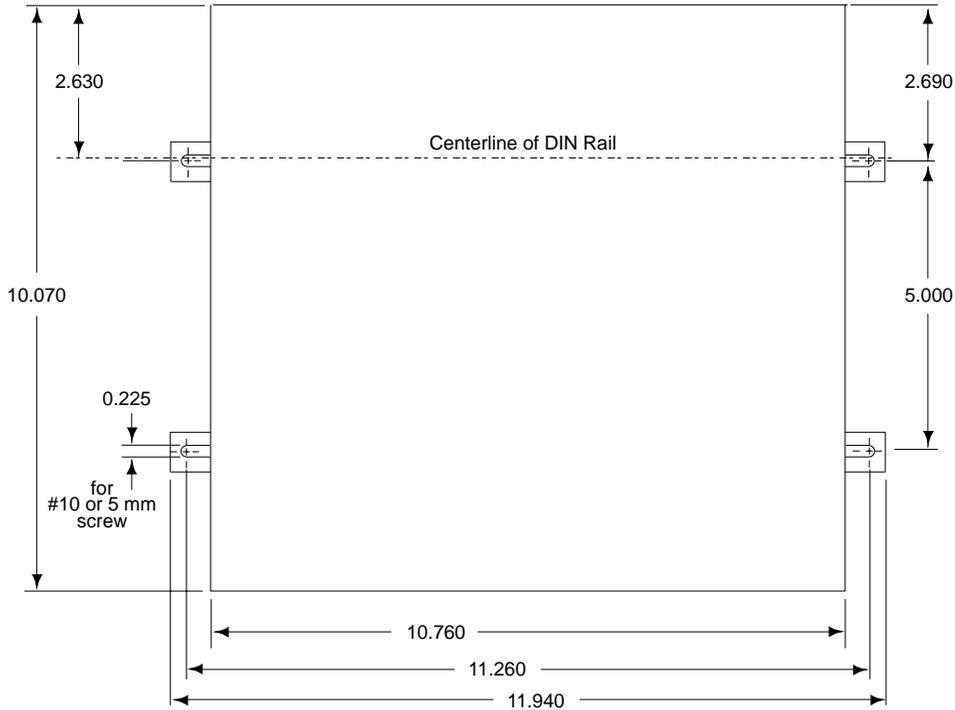
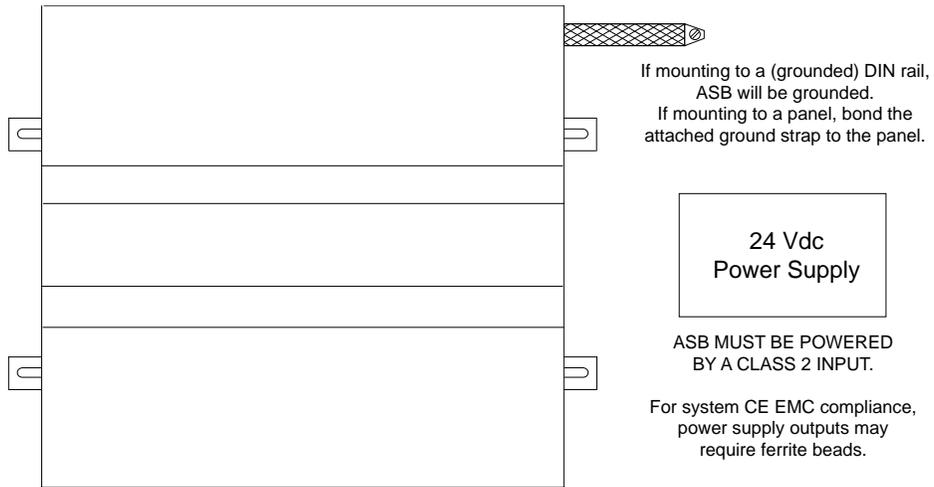
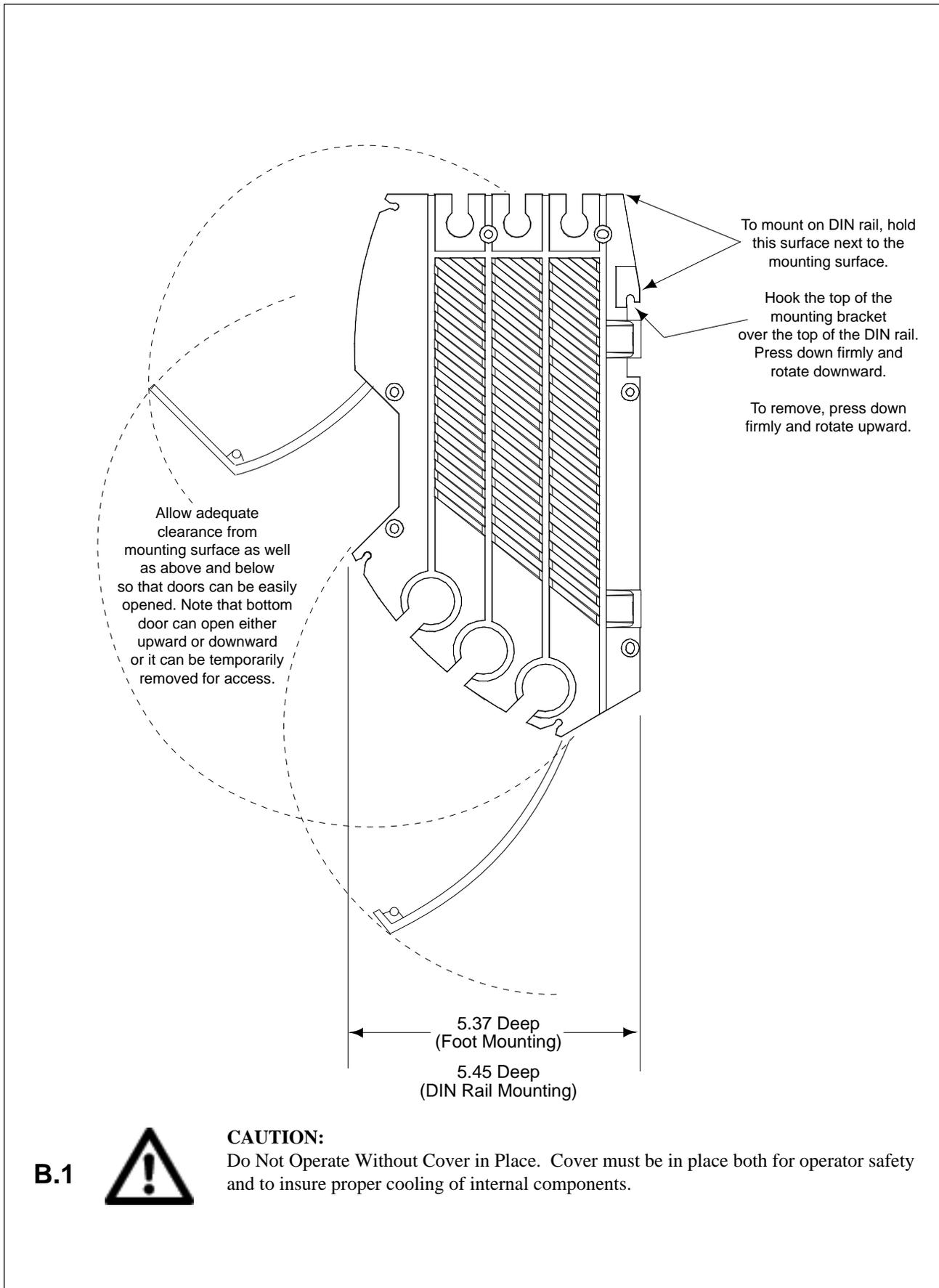


Figure 1. ASB Mounting (front view)



B.1



CAUTION:
Do Not Operate Without Cover in Place. Cover must be in place both for operator safety and to insure proper cooling of internal components.

Figure 2. ASB Mounting (side view)

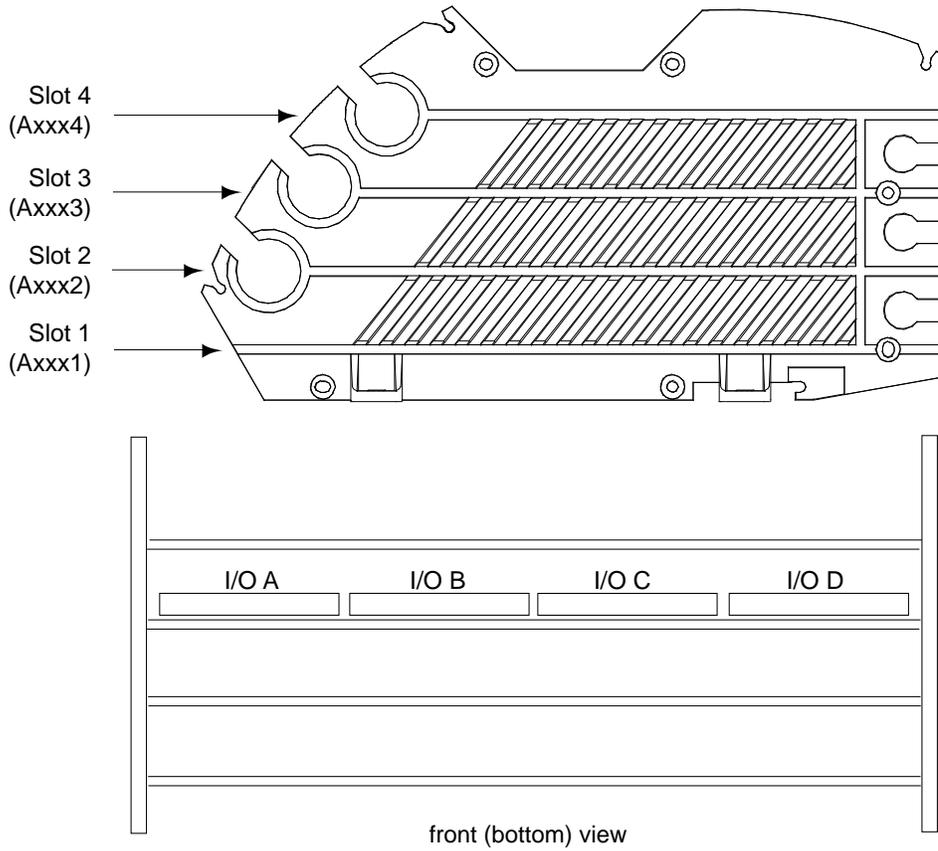


Figure 3. ASB Slot Numbering

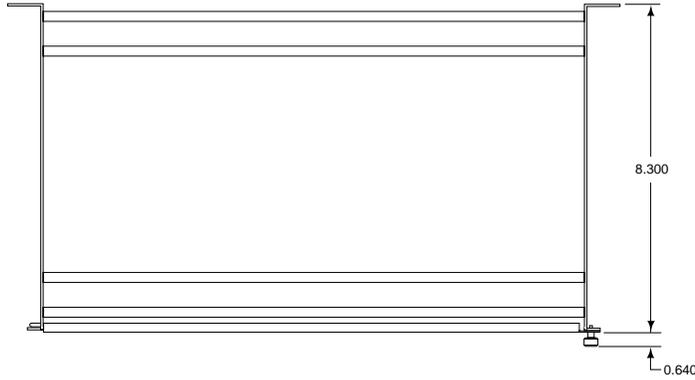
Include a switch or circuit breaker in the installation. It must be placed in close proximity to the equipment, within easy reach of the operator and must be marked as the disconnecting device for the equipment.

A.1



CAUTION:

Risk of Electric Shock - More than one disconnect switch may be required to deenergize the equipment before servicing.



Note that the RS Rack achieves a ground connection by bonding the rack to a grounded panel by means of the rack's mounting screws.

24 Vdc
Power Supply

RS Rack MUST BE POWERED BY A CLASS 2 INPUT.

For system CE EMC compliance, power supply outputs may require ferrite beads.

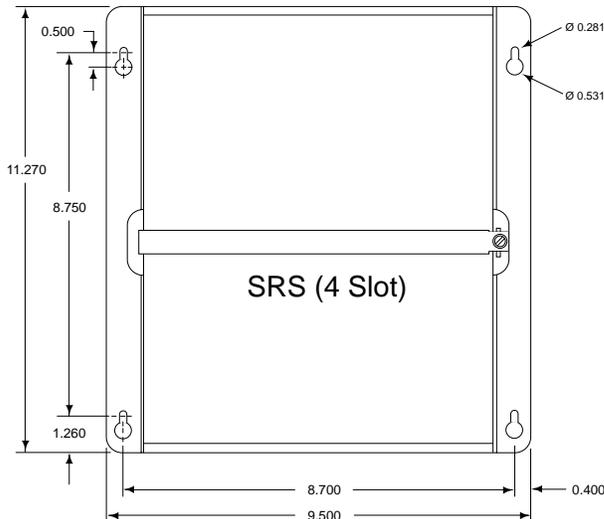
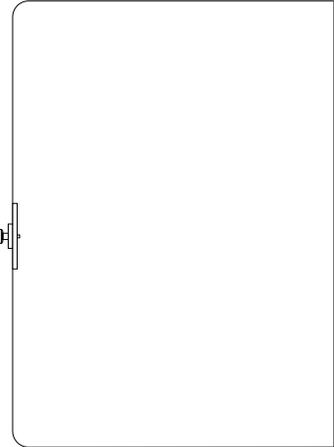
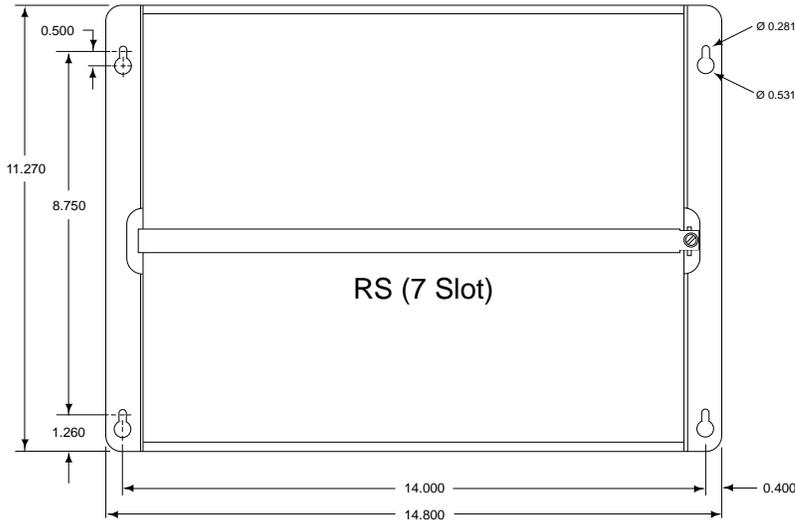
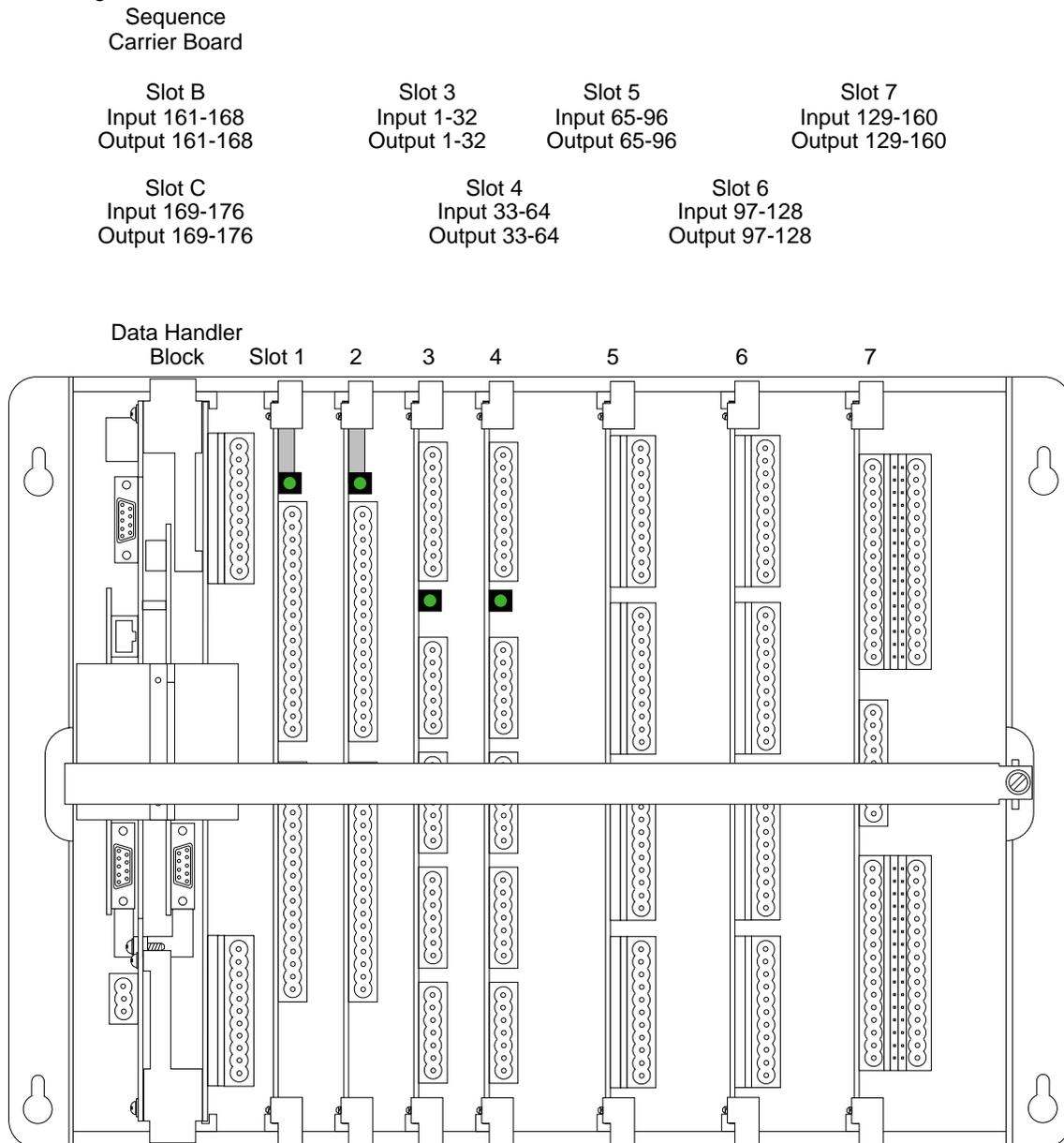


Figure 4. RS and SRS Rack Mounting

I/O Numbering



Notes:

1. Slots 1-4 can be T/C-Analog, maximum of 4 per rack.
2. Slots 2-4 can be Parison, EZ PRO, Injection or Extrusion, maximum of 2 per rack.
3. Slots 3-7 can be 32 I/O or 24 I/O Card assemblies.
4. Slots 3-7 can be 4-slot Carrier Boards, maximum of 2 Carrier Boards per rack.

Figure 5. RS Rack Slot Numbering

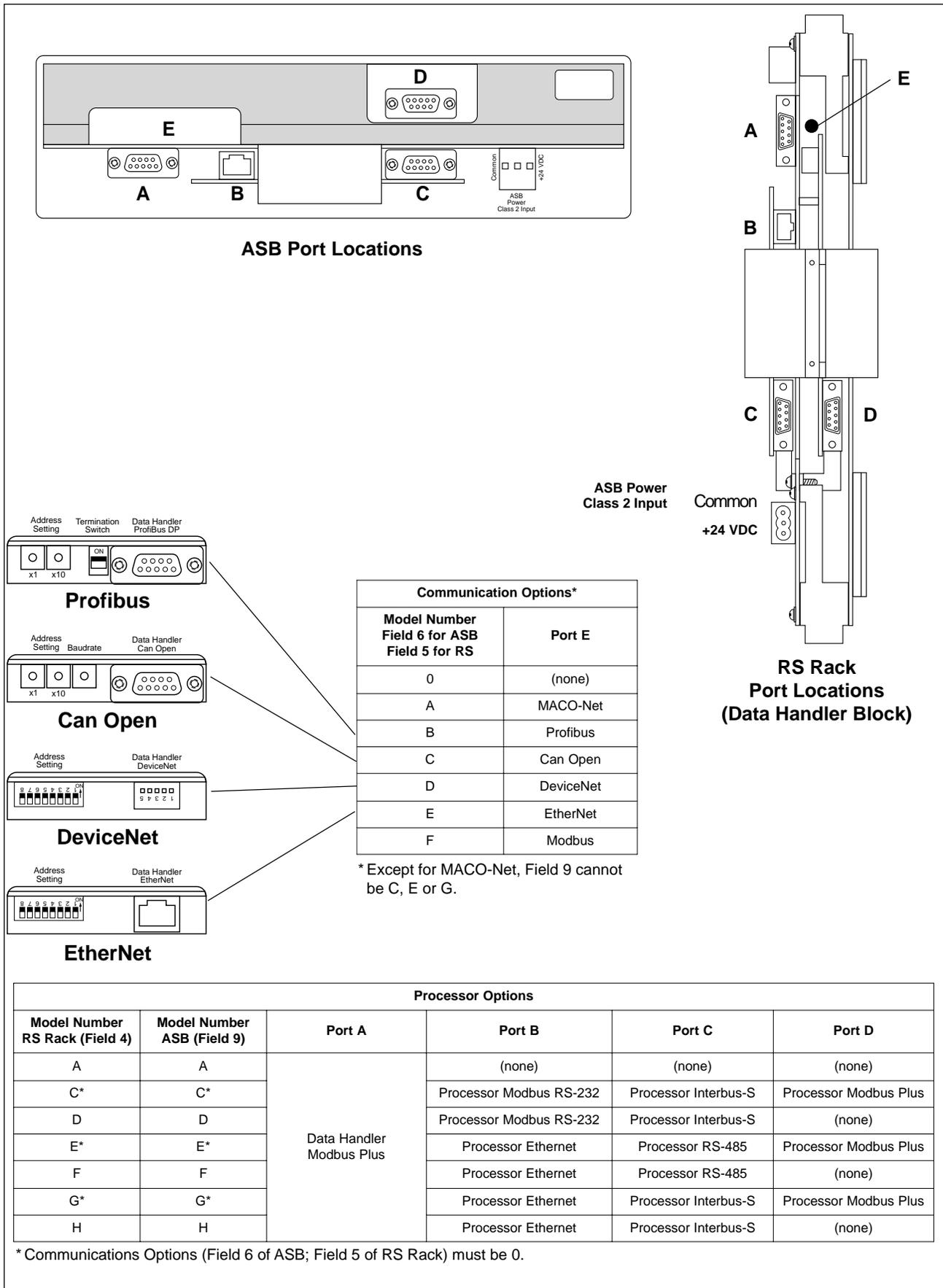
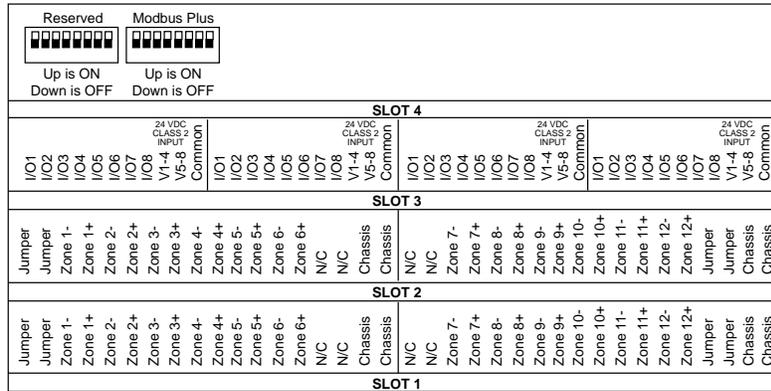


Figure 6. Processor and Communication Options



2. Wiring the Data Handler Board

Check all switch settings. See page 4 or 7 for power supply requirements.

C.1

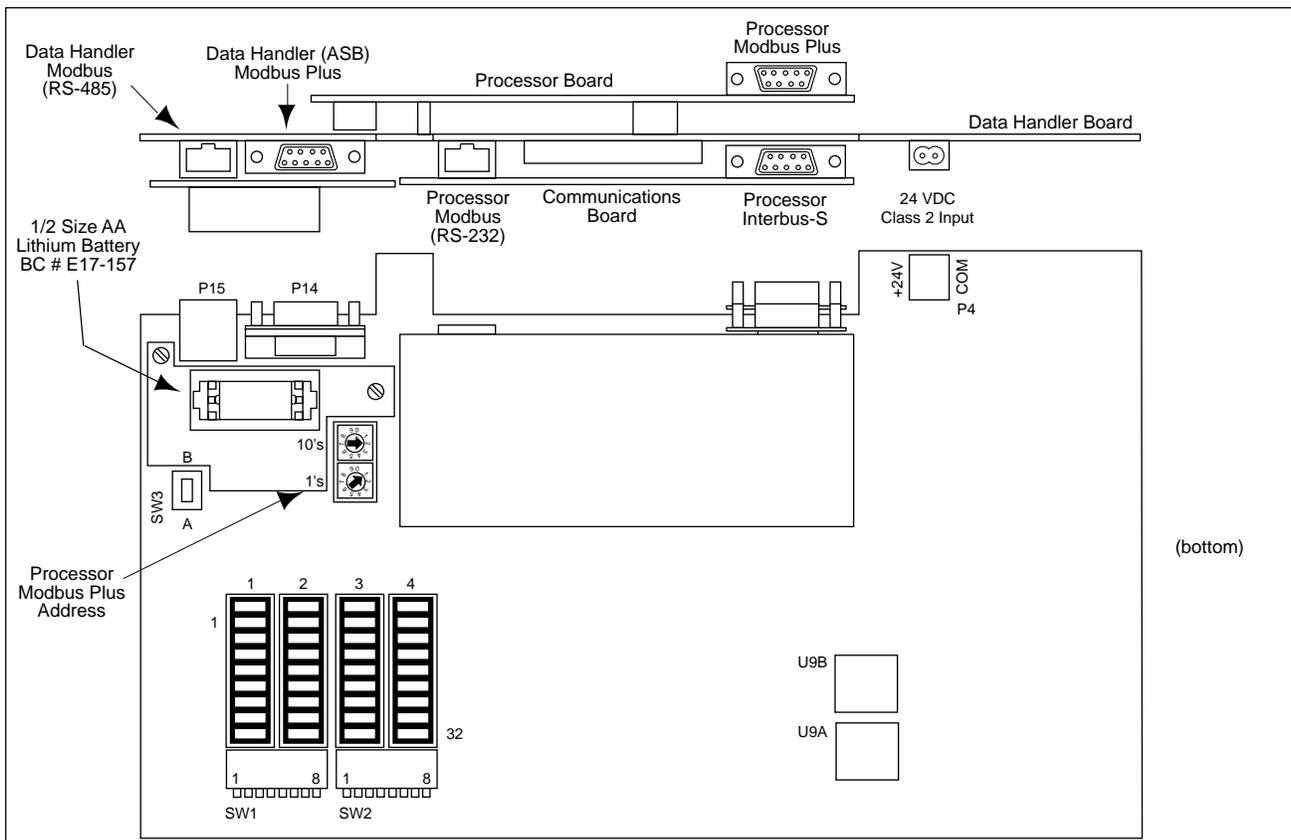


WARNING:

Use of improper battery could present a risk of fire or explosion of the battery.

| Address Number (binary + 1) | Switch 1 (bit 0) | Switch 2 (bit 1) | Switch 3 (bit 2) | Switch 4 (bit 3) | Switch 5 (bit 4) | Switch 6 (bit 5) |
|--------------------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| 1 | Off | Off | Off | Off | Off | Off |
| 2 | On | Off | Off | Off | Off | Off |
| 3 | Off | On | Off | Off | Off | Off |
| 4 | On | On | Off | Off | Off | Off |
| 5 | Off | Off | On | Off | Off | Off |
| 6 | On | Off | On | Off | Off | Off |
| 7 | Off | On | On | Off | Off | Off |
| 8 | On | On | On | Off | Off | Off |
| 9 | Off | Off | Off | On | Off | Off |
| 10 | On | Off | Off | On | Off | Off |
| 11 | Off | On | Off | On | Off | Off |
| 12 | On | On | Off | On | Off | Off |
| 13 | Off | Off | On | On | Off | Off |
| 14 | On | Off | On | On | Off | Off |
| 15 | Off | On | On | On | Off | Off |
| 16 | On | On | On | On | Off | Off |
| 17 | Off | Off | Off | Off | On | Off |
| 18 | On | Off | Off | Off | On | Off |
| 19 | Off | On | Off | Off | On | Off |
| 20 | On | On | Off | Off | On | Off |

Table 1. Switch Settings for Modbus and Modbus Plus Addressing



(bottom)

| SW1 (ASB Modbus Address) | |
|----------------------------|-------------------------|
| Switch Number | Assignment |
| 1 | bit 0 (On = 1; Off = 0) |
| 2 | bit 1 (On = 1; Off = 0) |
| 3 | bit 2 (On = 1; Off = 0) |
| 4 | bit 3 (On = 1; Off = 0) |
| 5 | bit 4 (On = 1; Off = 0) |
| 6 | bit 5 (On = 1; Off = 0) |
| 7 | not used |
| 8 | not used |
| Address = binary total + 1 | |

| SW2 (ASB Modbus Plus Address) | |
|-------------------------------|-------------------------|
| Switch Number | Assignment |
| 1 | bit 0 (On = 1; Off = 0) |
| 2 | bit 1 (On = 1; Off = 0) |
| 3 | bit 2 (On = 1; Off = 0) |
| 4 | bit 3 (On = 1; Off = 0) |
| 5 | bit 4 (On = 1; Off = 0) |
| 6 | bit 5 (On = 1; Off = 0) |
| 7 | not used |
| 8 | not used |
| Address = binary total + 1 | |

| SW3 (Data Handler Modbus Termination) | |
|---------------------------------------|--------------|
| Switch Position | Assignment |
| A | unterminated |
| B | terminated |

| P4 | |
|------------------|------------|
| Pin Number | Assignment |
| 1 | COM |
| 2 | +24 VDC |
| Mating Connector | E24-1497 |

Modbus Plus Addresses:

(ASB's = 1-20)
 ASB #1 = Address 1
 ASB #2 = Address 2
 ASB #3 = Address 3
 ASB #4 = Address 4
 " "

(Internal PLC's = 21-40)
 Internal PLC (Processor) #1 = Address 21
 Internal PLC (Processor) #2 = Address 22
 Internal PLC (Processor) #3 = Address 23
 Internal PLC (Processor) #4 = Address 24
 " "

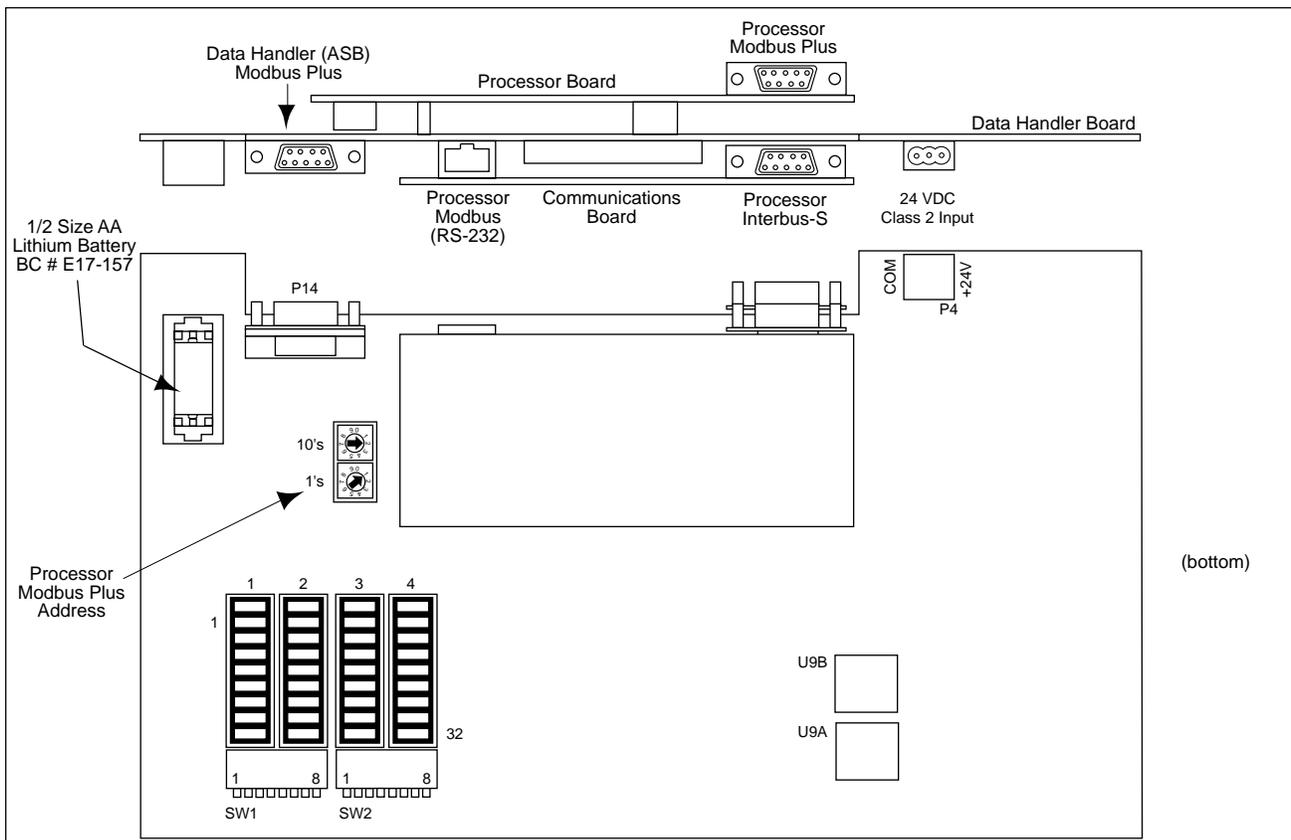
(External PLC's and Other = 41-60)
 External PLC (Processor) #1 = Address 41
 External PLC (Processor) #2 = Address 42
 External PLC (Processor) #3 = Address 43
 External PLC (Processor) #4 = Address 44
 " "

(OPTIMA PC = 61)

(Other Operator Stations = 62-64)

| LED's | | | |
|--------|------------------------|-------------------|--------------------------|
| +5V ON | ASB Modbus Plus Active | ASB Modbus Active | ASB Control Fault Active |
| LED_01 | LED_09 | LED_17 | LED_25 |
| LED_02 | LED_10 | LED_18 | LED_26 |
| LED_03 | LED_11 | LED_19 | LED_27 |
| LED_04 | LED_12 | LED_20 | LED_28 |
| LED_05 | LED_13 | LED_21 | LED_29 |
| LED_06 | LED_14 | LED_22 | LED_30 |
| LED_07 | LED_15 | LED_23 | LED_31 |
| LED_08 | LED_16 | LED_24 | LED_32 |

Figure 9.1 Data Handler Card A-60134-xx1



(bottom)

| SW1 | |
|----------------------------|-------------------------|
| Modbus Address | |
| Switch Number | Assignment |
| 1 | bit 0 (On = 1; Off = 0) |
| 2 | bit 1 (On = 1; Off = 0) |
| 3 | bit 2 (On = 1; Off = 0) |
| 4 | bit 3 (On = 1; Off = 0) |
| 5 | bit 4 (On = 1; Off = 0) |
| 6 | bit 5 (On = 1; Off = 0) |
| Address = binary total + 1 | |
| 7 | not used |
| Controller Type | |
| 8 | Off = DS, On = RS |

| SW2 | |
|----------------------------|-------------------------|
| Modbus Plus Address | |
| Switch Number | Assignment |
| 1 | bit 0 (On = 1; Off = 0) |
| 2 | bit 1 (On = 1; Off = 0) |
| 3 | bit 2 (On = 1; Off = 0) |
| 4 | bit 3 (On = 1; Off = 0) |
| 5 | bit 4 (On = 1; Off = 0) |
| 6 | bit 5 (On = 1; Off = 0) |
| Address = binary total + 1 | |
| 7 | not used |
| 8 | not used |

| P4 | |
|------------------|--------------|
| Pin Number | Assignment |
| 1 | +24 VDC |
| 2 | Not Used |
| 3 | COM |
| Mating Connector | E24-1134-003 |

| LED's | | | |
|--------|------------------------|-------------------|--------------------------|
| +5V ON | ASB Modbus Plus Active | ASB Modbus Active | ASB Control Fault Active |
| LED_01 | LED_09 | LED_17 | LED_25 |
| LED_02 | LED_10 | LED_18 | LED_26 |
| LED_03 | LED_11 | LED_19 | LED_27 |
| LED_04 | LED_12 | LED_20 | LED_28 |
| LED_05 | LED_13 | LED_21 | LED_29 |
| LED_06 | LED_14 | LED_22 | LED_30 |
| LED_07 | LED_15 | LED_23 | LED_31 |
| LED_08 | LED_16 | LED_24 | LED_32 |

Modbus Plus Addresses:

(ASB's = 1-20)
 ASB #1 = Address 1
 ASB #2 = Address 2
 ASB #3 = Address 3
 ASB #4 = Address 4
 " " " "

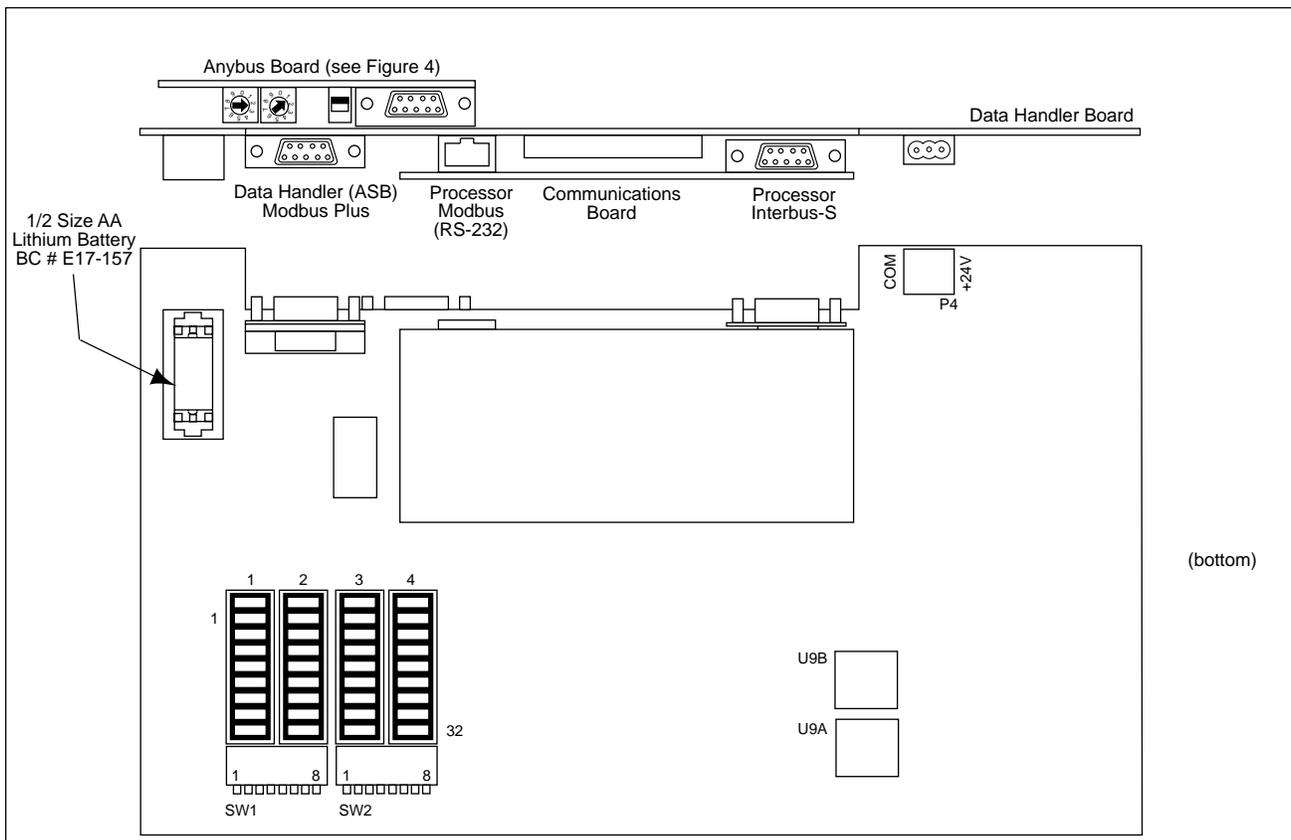
(Internal PLC's = 21-40)
 Internal PLC (Processor) #1 = Address 21
 Internal PLC (Processor) #2 = Address 22
 Internal PLC (Processor) #3 = Address 23
 Internal PLC (Processor) #4 = Address 24
 " " " "

(External PLC's and Other = 41-60)
 External PLC (Processor) #1 = Address 41
 External PLC (Processor) #2 = Address 42
 External PLC (Processor) #3 = Address 43
 External PLC (Processor) #4 = Address 44
 " " " "

(OPTIMA PC = 61)

(Other Operator Stations = 62-64)

Figure 9.2 Data Handler Card A-60149 with Processor



| SW1 | |
|----------------------------|-------------------------|
| Modbus Address | |
| Switch Number | Assignment |
| 1 | bit 0 (On = 1; Off = 0) |
| 2 | bit 1 (On = 1; Off = 0) |
| 3 | bit 2 (On = 1; Off = 0) |
| 4 | bit 3 (On = 1; Off = 0) |
| 5 | bit 4 (On = 1; Off = 0) |
| 6 | bit 5 (On = 1; Off = 0) |
| Address = binary total + 1 | |
| 7 | not used |
| Controller Type | |
| 8 | Off = DS, On = RS |

| SW2 | |
|----------------------------|-------------------------|
| Modbus Plus Address | |
| Switch Number | Assignment |
| 1 | bit 0 (On = 1; Off = 0) |
| 2 | bit 1 (On = 1; Off = 0) |
| 3 | bit 2 (On = 1; Off = 0) |
| 4 | bit 3 (On = 1; Off = 0) |
| 5 | bit 4 (On = 1; Off = 0) |
| 6 | bit 5 (On = 1; Off = 0) |
| Address = binary total + 1 | |
| 7 | not used |
| 8 | not used |

| P4 | |
|------------------|--------------|
| Pin Number | Assignment |
| 1 | +24 VDC |
| 2 | Not Used |
| 3 | COM |
| Mating Connector | E24-1134-003 |

| LED's | | | |
|--------|------------------------|-------------------|--------------------------|
| +5V ON | ASB Modbus Plus Active | ASB Modbus Active | ASB Control Fault Active |
| LED_01 | LED_09 | LED_17 | LED_25 |
| LED_02 | LED_10 | LED_18 | LED_26 |
| LED_03 | LED_11 | LED_19 | LED_27 |
| LED_04 | LED_12 | LED_20 | LED_28 |
| LED_05 | LED_13 | LED_21 | LED_29 |
| LED_06 | LED_14 | LED_22 | LED_30 |
| LED_07 | LED_15 | LED_23 | LED_31 |
| LED_08 | LED_16 | LED_24 | LED_32 |

Modbus Plus Addresses:

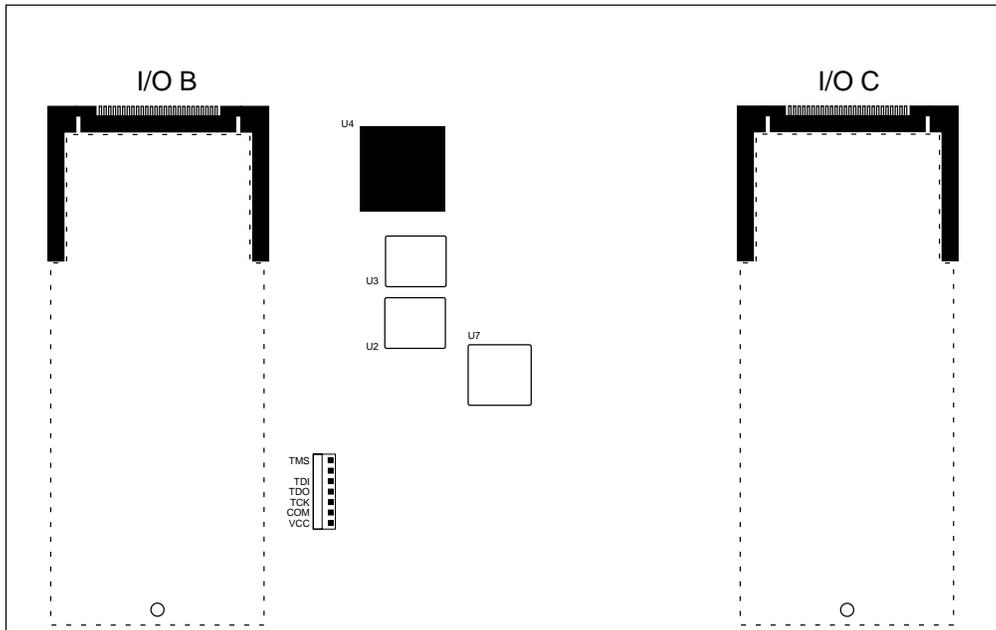
(ASB's = 1-20)
 ASB #1 = Address 1
 ASB #2 = Address 2
 ASB #3 = Address 3
 ASB #4 = Address 4
 " " " "

(External PLC's and Other = 41-60)
 External PLC (Processor) #1 = Address 41
 External PLC (Processor) #2 = Address 42
 External PLC (Processor) #3 = Address 43
 External PLC (Processor) #4 = Address 44
 " " " "

(OPTima PC = 61)

(Other Operator Stations = 62-64)

Figure 9.3 Data Handler Card A-60149 with Anybus Card



(bottom)

Slots B and C are normally used for communications boards (MACO-Net, Modbus), but can be used for any plug-in boards. If a MACO-Net card is used, it should reside Slot C of of this board in Node 1 of the system (and if the system consists of ASBs and Rack systems, a Rack system should be Node 1). Refer to the 4-slot carrier board for wiring details.

Figure 9.4 Two Slot Carrier/Sequence Board (Rack Systems only)

3. Wiring the T/C-Analog Board

Make certain to use the proper extension wire. Do NOT run extension wire in the same trough with power wiring.

Note that these boards cannot be calibrated in the field.

If the analog inputs are to be used as CURRENT inputs, first install one resistor (505 Ω , 1/2 W, 0.1%, 25 ppm) from kit number 71-975 across the plus and minus of each input and then wire to the terminals specified.

The A-60133-8xx board (with 3 analog inputs) is NOT meant to be used for millivolt input on the 3 analog inputs. It is designed for a 0 to 10 Vdc input which is then INTERNALLY attenuated to 0 to 40 mVdc (note that the analog inputs can be converted to CURRENT inputs using the resistors described above). When configuring the board for use, enter a TC_Analog_Config_Z7_Z12 setpoint that is correct for Zones 7-9. In addition, enter a PID_Tuning_Selection setpoint of "4" for Zones 10-12.

T/C-Analog Card Specifications

Isolation:

Inputs are isolated channel to channel

Reference Accuracy:

0.25% of Span, $\pm 1^\circ\text{C}$

Common Mode Rejection:

135 dB @ 230 Vac 60Hz

Range:

Type J, 0 to 700°C (32 to 1292°F)
Type J DIN, 0 to 700°C (32 to 1292°F)
Type K, 0 to 950°C (32 to 1742°F)
0 to 10 Vdc
0 to 20 mAdc (scalable)

Series Mode Rejection:

60 dB @ 150 mV 60 Hz

Control Zones:

| | |
|-------------|--|
| A-60133-4XX | 12 Zones of T/C Input |
| A-60133-5XX | 12 Zones of Analog Input (Vdc or mAdc) |
| A-60133-6XX | Zones 1-6 Analog Input (Vdc or mAdc) Zones 7-12 T/C Input |
| A-60133-7XX | 6 Zones of T/C Input |
| A-60133-8XX | Zones 1-9 T/C Input Zones 10-12 Analog In (Vdc) |

Alarms:

2 Process High/ 1 Process Low
Deviation +/-
Sensor Break
Heater Burnout (HBO, T/C inputs only)

Control Modes:

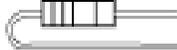
Auto-Tuned PID (T/C Inputs only)
Manual Tune (T/C Inputs only)

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

Kit No. 71-975 consists of six 505 Ω , 1/2 W, 0.1%, 25 ppm resistors

| T/C-Analog Assembly | No. of Kits |
|--|-----------------------|
| A-60133-5XX (12 Zones of Analog Input) | 2 Kits (12 Resistors) |
| A-60133-6XX (6 Zones of Analog Input) | 1 Kit (6 Resistors) |

Install these resistors ONLY on the assemblies shown above AND ONLY if the inputs to the assembly are CURRENT (mA_{dc}) instead of voltage.



Cut and form the resistors approximately as shown. Insert one resistor lead with the plus (+) side of the input and the other with the minus (-) side. Before applying power, examine all leads for possible short circuits.

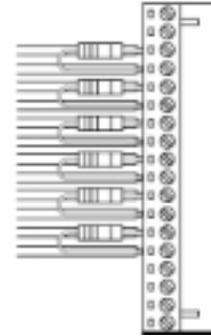
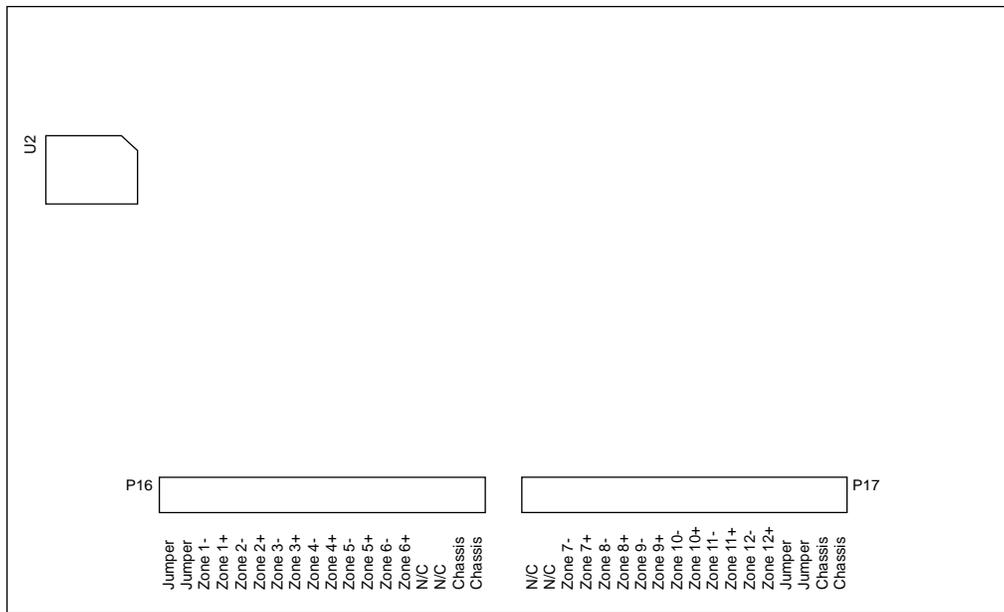


Figure 10. Installing Resistors for Current Inputs



| Pin Number | P16 | | | | |
|------------------|---------------------------------|-------------|-------------|-------------|-------------|
| | A-60133-4xx | A-60133-5xx | A-60133-6xx | A-60133-7xx | A-60133-8xx |
| | Assignment | | | | |
| 1 | Not Used | Not Used | Not Used | Not Used | Not Used |
| 2 | Not Used | Not Used | Not Used | Not Used | Not Used |
| 3 | T/C 1 - | Ana 1 - | Ana 1 - | T/C 1 - | T/C 1 - |
| 4 | T/C 1 + | Ana 1 + | Ana 1 + | T/C 1 + | T/C 1 + |
| 5 | T/C 2 - | Ana 2 - | Ana 2 - | T/C 2 - | T/C 2 - |
| 6 | T/C 2 + | Ana 2 + | Ana 2 + | T/C 2 + | T/C 2 + |
| 7 | T/C 3 - | Ana 3 - | Ana 3 - | T/C 3 - | T/C 3 - |
| 8 | T/C 3 + | Ana 3 + | Ana 3 + | T/C 3 + | T/C 3 + |
| 9 | T/C 4 - | Ana 4 - | Ana 4 - | T/C 4 - | T/C 4 - |
| 10 | T/C 4 + | Ana 4 + | Ana 4 + | T/C 4 + | T/C 4 + |
| 11 | T/C 5 - | Ana 5 - | Ana 5 - | T/C 5 - | T/C 5 - |
| 12 | T/C 5 + | Ana 5 + | Ana 5 + | T/C 5 + | T/C 5 + |
| 13 | T/C 6 - | Ana 6 - | Ana 6 - | T/C 6 - | T/C 6 - |
| 14 | T/C 6 + | Ana 6 + | Ana 6 + | T/C 6 + | T/C 6 + |
| 15 | Jumper | Jumper | Jumper | Jumper | Jumper |
| 16 | Jumper | Jumper | Jumper | Jumper | Jumper |
| 17 | Chassis Ground (do NOT connect) | | | | |
| 18 | Chassis Ground (do NOT connect) | | | | |
| Mating Connector | E24-1134-018 | | | | |

| Pin Number | P17 | | | | |
|------------------|---------------------------------|-------------|-------------|-------------|-------------|
| | A-60133-4xx | A-60133-5xx | A-60133-6xx | A-60133-7xx | A-60133-8xx |
| | Assignment | | | | |
| 1 | Not Used | Not Used | Not Used | Not Used | Not Used |
| 2 | Not Used | Not Used | Not Used | Not Used | Not Used |
| 3 | T/C 7 - | Ana 7 - | T/C 7 - | n/a | T/C 7 - |
| 4 | T/C 7 + | Ana 7 + | T/C 7 + | n/a | T/C 7 + |
| 5 | T/C 8 - | Ana 8 - | T/C 8 - | n/a | T/C 8 - |
| 6 | T/C 8 + | Ana 8 + | T/C 8 + | n/a | T/C 8 + |
| 7 | T/C 9 - | Ana 9 - | T/C 9 - | n/a | T/C 9 - |
| 8 | T/C 9 + | Ana 9 + | T/C 9 + | n/a | T/C 9 + |
| 9 | T/C 10 - | Ana 10 - | T/C 10 - | n/a | Ana 10 - |
| 10 | T/C 10 + | Ana 10 + | T/C 10 + | n/a | Ana 10 + |
| 11 | T/C 11 - | Ana 11 - | T/C 11 - | n/a | Ana 11 - |
| 12 | T/C 11 + | Ana 11 + | T/C 11 + | n/a | Ana 11 + |
| 13 | T/C 12 - | Ana 12 - | T/C 12 - | n/a | Ana 12 - |
| 14 | T/C 12 + | Ana 12 + | T/C 12 + | n/a | Ana 12 + |
| 15 | Jumper | Jumper | Jumper | Jumper | Jumper |
| 16 | Jumper | Jumper | Jumper | Jumper | Jumper |
| 17 | Chassis Ground (do NOT connect) | | | | |
| 18 | Chassis Ground (do NOT connect) | | | | |
| Mating Connector | E24-1134-018 | | | | |

D.1



WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

Figure 11. T/C-Analog Card A-60133-xx1

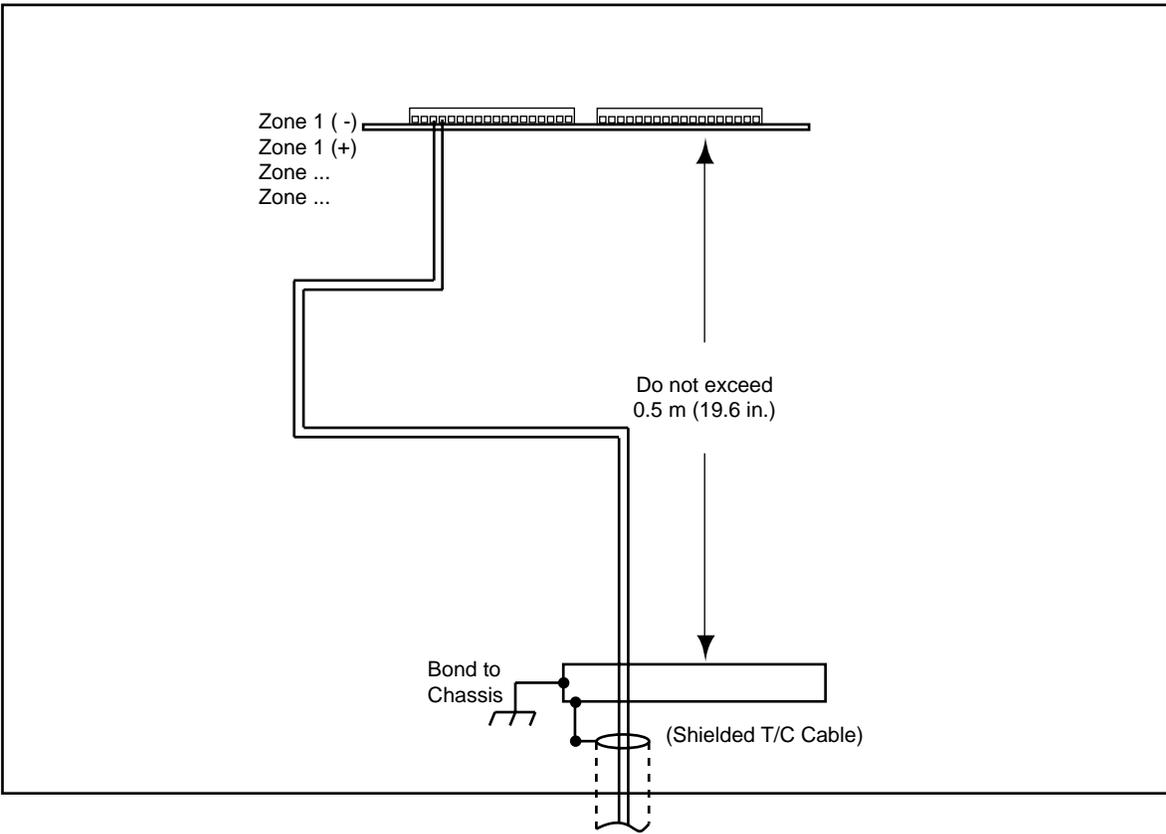


Figure 12. Wiring Thermocouple Inputs using the T/C-Analog Card

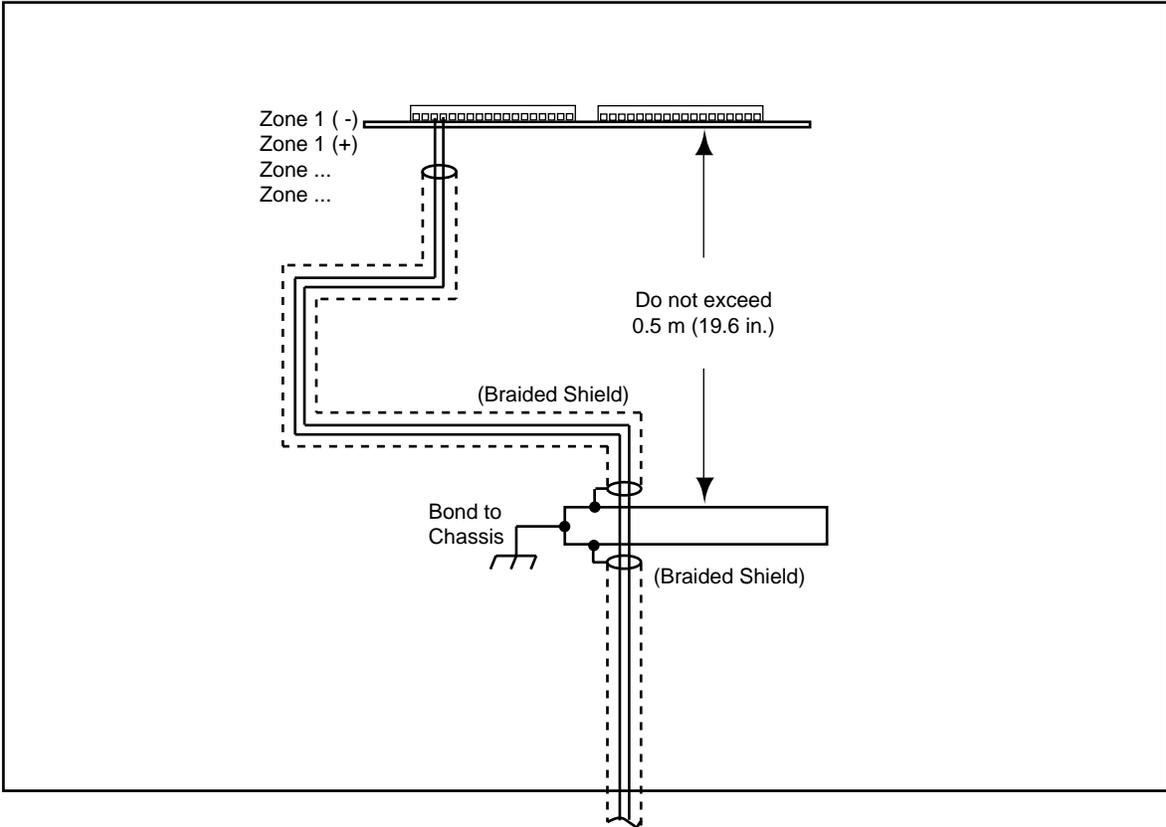


Figure 13. Wiring Analog Inputs using the T/C-Analog Card

4. Wiring the High Speed Analog (Parison, EZ PRO, Injection) Board

4.1 Introduction

The high speed analog card can be specified with 1, 2, or 4 channels of control. The number of channels required will depend on the amount of control needed by the process. Regardless of the number of channels specified, wiring from one channel to another will be similar (the difference being the type of sensor used to provide the input). Current or voltage inputs can be used. Outputs are voltage only and are intended for use with a drive package or amplifier.

4.2 Analog Input/Output Wiring Guidelines

1. Use braided shield cables on ALL analog inputs and outputs. Use separate cables for each function and keep cables less than 3 meters in length. If cables are over 3 meters long, an overbraid is required. If overbraid has been used, terminate both the internal braided shield and the overbraid at the ground distribution block.

2. Analog Input (-) must be connected to Analog Common at the sensing device to prevent ground loop currents.

3. Excitation voltage for potentiometers is provided by the card. Excitation voltage is +10 Vdc @ 20 mA. Potentiometer resistance should be 500Ω to 2kΩ.

4.2.1 Injection Control Ram Position and Ram Pressure Inputs

Normally:

ANA IN1 = Ram Position
ANA IN2 = Ram Pressure
ANA IN3 = Clamp Position
ANA IN4 = Ejector Position

(see text)

If this card is to be used for Injection Process Control, under normal conditions, the Ram Position Input must be connected to ANA IN1 and the Ram Pressure Input must be connected to ANA IN2. The exception would be if there were non-zero entries used for the Ram_Position_Reg_Id or Ram_Pressure_Reg_Id setpoints:

A zero (default) entry for the Ram_Position_Reg_Id setpoint causes the software to use ANA IN1 (the Loop_1_Process_Value) as the Ram Position input.

A non-zero entry for the Ram_Position_Reg_Id setpoint causes the software to use that non-zero entry (which is actually the item name minus 400,000) to locate the alternate source for the Ram Position input.

A zero (default) entry for the Ram_Velocity_Reg_Id setpoint causes the software to use the rate of change of ANA IN 1 as the Ram Velocity input.

A non-zero entry for the Ram_Velocity_Reg_Id setpoint causes the software to use that non-zero entry (which is actually the item name minus 400,000) to locate the alternate source for the Ram Velocity input. *Note that even if the Ram Position input has been redirected, Ram Velocity will STILL be derived from ANA IN 1 as long as the Ram_Velocity_Reg_Id setpoint is zero.*

A zero (default) entry for the Ram_Pressure_Reg_Id setpoint causes the software to use ANA IN2 (the Loop_2_Process_Value) as the Ram Pressure input.

A non-zero entry for the Ram_Pressure_Reg_Id setpoint causes the software to use that non-zero entry (which is actually the item name minus 400,000) to locate the alternate source for the Ram Pressure input.

4.2.2 EZ PRO Version 13.08 Changes Relating to Switch 3

If this card is to be used for position control (EZ PRO), note the following changes that occur with the advent of Version 13.08 firmware:

“Axis_n_Lock_Alarm” Action

The following changes were implemented in order to allow the selection of the course of action if an “Axis_n_Lock_Alarm” occurs for lockup timeout, lockup deviation, or sensor out of range.

Two conditions can cause a lock alarm:

Condition 1, the time from when creep begins until the lockup is achieved exceeds the “Axis_n_LckupTimOut” setpoint.

Condition 2, once lockup is achieved the “Axis_n_Lockup_Devn” setpoint is violated.

With previous firmware when either condition occurs the “Axis_n_Lock_Alarm” is set and the control determines a new target position to CLOSED LOOP POSITION control that will be near the position of the fault. Even though the control may have been in open loop lockup, if the alarm is set, control will revert to closed loop position control. This method remains the default action of the firmware.

Version 13.08 firmware allows for selection of an alternate reaction to the “Axis n Lock Alarm” conditions. For the first fault condition (not achieving lock position in time) the target for the position control remains as the target of the motion. For the second fault condition (an alarm caused by a lockup deviation violation) the loop maintains the open loop lock output.

Selection of the alternate actions is by one of two means:

First, if Switch 3 on the card is placed in the OPEN position, ALL axis on the card will use the alternate actions.

Second, the alternate action can be individually selected for each axis by setpoint. If the setpoint method is used, then the action for an alarm caused by “Axis_n LckupTimOut” is chosen by means of the “Axis_n_Creep_Mode_Sel” setpoint; the action for an alarm caused by “Axis_n_Lockup_Devn” is chosen by means of the “Axis_n_Lock_Mode_Sp_y” setpoint.

To select the alternate method using the “Axis_n_Creep_Mode_Sel” setpoint, simply add “8” to the previously defined numeric mode (i.e., if the “Axis_n_Creep_Mode_Sel” setpoint had been 3, and the alternate method of handling the alarm condition in creep is desired, an “11” would be entered).

To select the alternate method using the “Axis_n_Lock_Mode_Sp_y” setpoint, enter “2” as the setpoint. An entry of “1” (as in previous versions) enables open loop lock at the end of motion.

Axis_n_E-Stop_Mode_Sel

The following conditions can be selected to cause an internal E-STOP condition:

- “Out_of_Range_n”
- “Axis_n_Motion_Alarm”
- “Axis_n_Lock_Alarm”
- “BrkAwy_Timeout_n”

With an internal e-stop, the axis is handled as if the e-stop was applied. But once an internal e-stop occurs, the axis is latched into that state and will remain there until the internal e-stop is overridden by energizing either “E-Stop_Axis_n” or an “Axis_n_Override_y” for the axis. The application of the user e-stop or the axis override indicates to the control that user logic has taken control of the fault/alarm condition. If the axis is disabled the internal e-stop latch condition is also cleared.

Switch 3 on the card placed in the OPEN position enables the internal e-stop action for the “Out_of_Range_n” condition for all axis of the card.

Individual selection can be made by entries to the “Axis_n_E-Stop_Mode_Sel” setpoint. This new setpoint is a bit-weighted selection in which each bit enables the internal e-stop for one of the 4 alarms.

| | | |
|-------|-----------------------|------|
| bit 0 | “Out_of_Range_n” | (+1) |
| bit 1 | “Axis_n_Motion_Alarm” | (+2) |
| bit 2 | “Axis_n_Lock_Alarm” | (+4) |
| bit 3 | “BrkAwy_Timeout n” | (+8) |

For example, for axis 1, if the internal e-stop action is desired for “Out_of_Range_1” and the “Axis_1_Lock_Alarm” then the setpoint entry for “Axis_1_E-Stop_Mode_Sel” would be $1 + 4 = 5$.

A setpoint entry of 0 for “Axis_n_E-Stop_Mode_Sel” with Switch 3 in the CLOSED position will also clear the internal e-stop condition.

4.3 Wiring DC Inputs & Outputs

The DC Input and Output functions require an external, regulated DC power supply capable of providing a nominal voltage of plus (+) 24 Vdc. The power supply must be CE recognized. The power supply and its ground distribution block must be located within 30 cm of the bottom of the controller chassis. There must be NO other (external) devices powered from the supply. The current rating of the power supply will depend on the loads being driven. Note that there are only four input and output functions and they are shared by all four channels if the card is so specified.

1. Connect (+)DC to Pin 5 of the top connector (P14). This supplies the voltage for the output circuits.
2. Connect (-)DC to Pin 6 of the same connector. This supplies DC Common for both the input and output circuits.
3. Connect the outputs to one side of the loads. Connect the other side of the loads to (-)DC.

18 gauge wire is recommended as a minimum, but make certain to satisfy all local and national code requirements.

4.4 Specifications

The following is a list of specifications that should be observed when installing and wiring this card. The specifications apply to all functions of the same type.

Analog Inputs

Input Signal:

± 10 Vdc (nominal) or ± 20 mA (nominal)(jumper selectable)

Input Impedance:

100k Ω minimum voltage input: 500 Ω current input

Input Function:

Accumulator Position, Die Position, or Hydraulic Pressure (user configurable)

Analog Outputs

Output Signal:

± 10 Vdc

Output Current:

4.5 mA maximum into a 2.2k ohm load

Input/Output Isolation:

Each Input/Output pair is isolated from all other pairs

DC Discrete Logic Inputs/Outputs

Isolation:

Optically isolated as a group

DC Inputs

Input Voltage:

-0.6 (minimum)
to 40 Vdc (maximum)

On Voltage:

10 Vdc

Off Voltage:

5 Vdc

Input Current

Less than 10 mA
at 24 Vdc

DC Outputs (Requires External Supply)

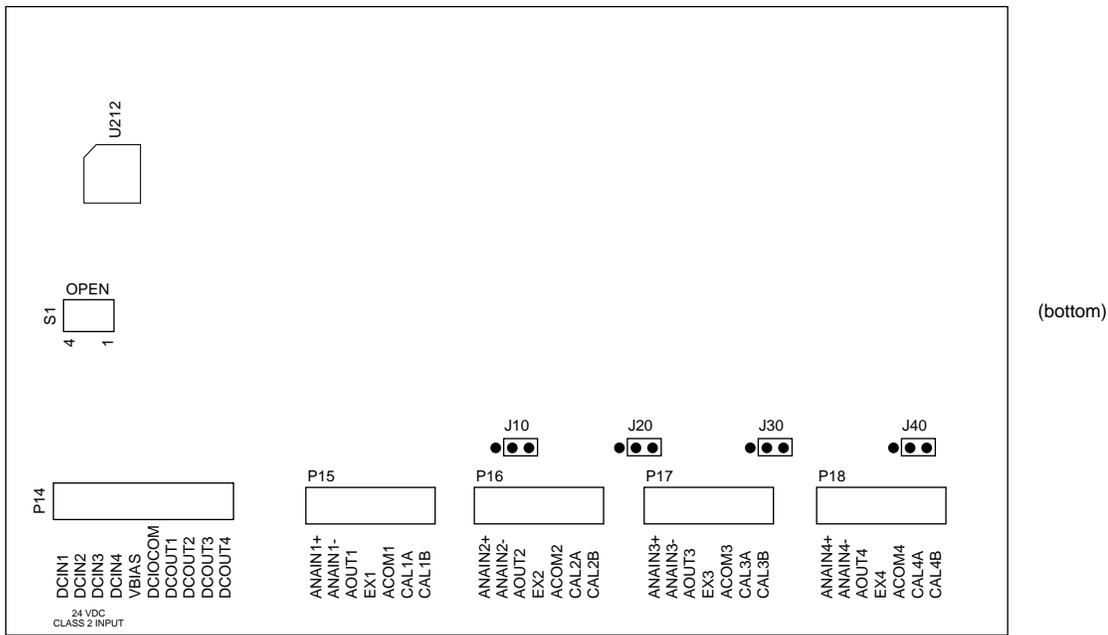
Voltage:

24 Vdc maximum
switched voltage

Current:

20 mA maximum
switched current

| |
|---|
| Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors. |
|---|



| P14 | |
|------------------|--------------|
| Pin Number | Assignment |
| 1 | DCIN1 |
| 2 | DCIN2 |
| 3 | DCIN3 |
| 4 | DCIN4 |
| 5 | VBIAS |
| 6 | DCIOCOM |
| 7 | DCOUT1 |
| 8 | DCOUT2 |
| 9 | DCOUT3 |
| 10 | DCOUT4 |
| Mating Connector | E24-1134-010 |

| | P15 | P16 | P17 | P18 |
|------------------|--------------|------------|------------|------------|
| Pin Number | Assignment | Assignment | Assignment | Assignment |
| 1 | ANAIN1+* | ANAIN2+* | ANAIN3+ | ANAIN4+ |
| 2 | ANAIN1-* | ANAIN2-* | ANAIN3- | ANAIN4- |
| 3 | AOUT1 | AOUT2 | AOUT3 | AOUT4 |
| 4 | EX1 | EX2 | EX3 | EX4 |
| 5 | ACOM1 | ACOM2 | ACOM3 | ACOM4 |
| 6 | CAL1A | CAL2A | CAL3A | CAL4A |
| 7 | CAL1B | CAL2B | CAL3B | CAL4B |
| Mating Connector | E24-1134-007 | | | |

*See text about using these inputs for Injection Process Control

| Jumper Number | Analog Inputs |
|---------------|-------------------------------|
| J10 | ANAIN1 = ±10 Volts* or ±20 mA |
| J20 | ANAIN2 = ±10 Volts* or ±20 mA |
| J30 | ANAIN3 = ±10 Volts* or ±20 mA |
| J40 | ANAIN4 = ±10 Volts* or ±20 mA |
| *as shipped | |

| Switch S1 | | | | |
|---------------|---|--------|--------|--------|
| Switch Number | Slot 1 | Slot 2 | Slot 3 | Slot 4 |
| 4 | Open = Run; Closed = Factory Cal | | | |
| 3 | (Ignored except when used as EZ PRO) Open = Use ALL EZ PRO V13.08 Alternate Actions Closed = Use EZ PRO V13.08 Alternate Actions by Setpoint Selection (see text) | | | |
| 2 | Closed | Closed | Open | Open |
| 1 | Closed | Open | Closed | Open |

D.1



WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

Figure 14. High Speed Analog (Parison, EZ PRO, Injection) Card A-60136-xx0

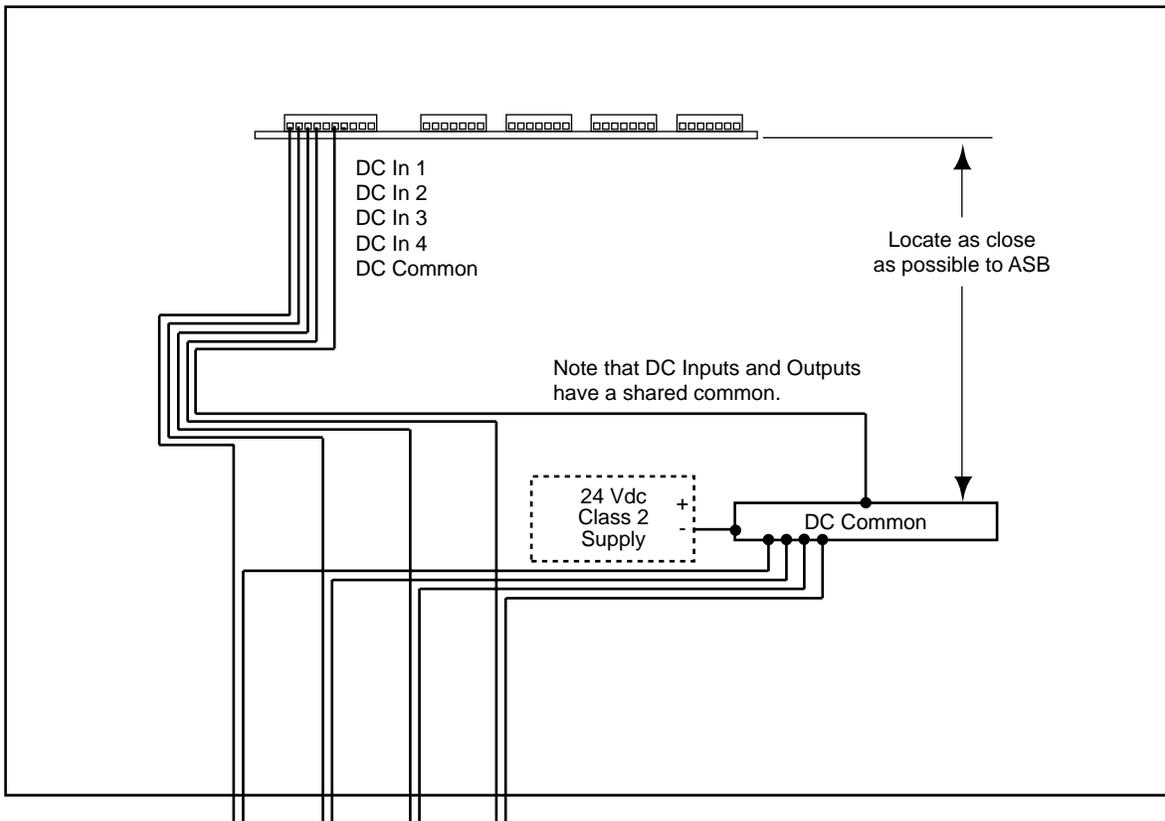


Figure 15. Wiring High Speed Analog Card DC Inputs

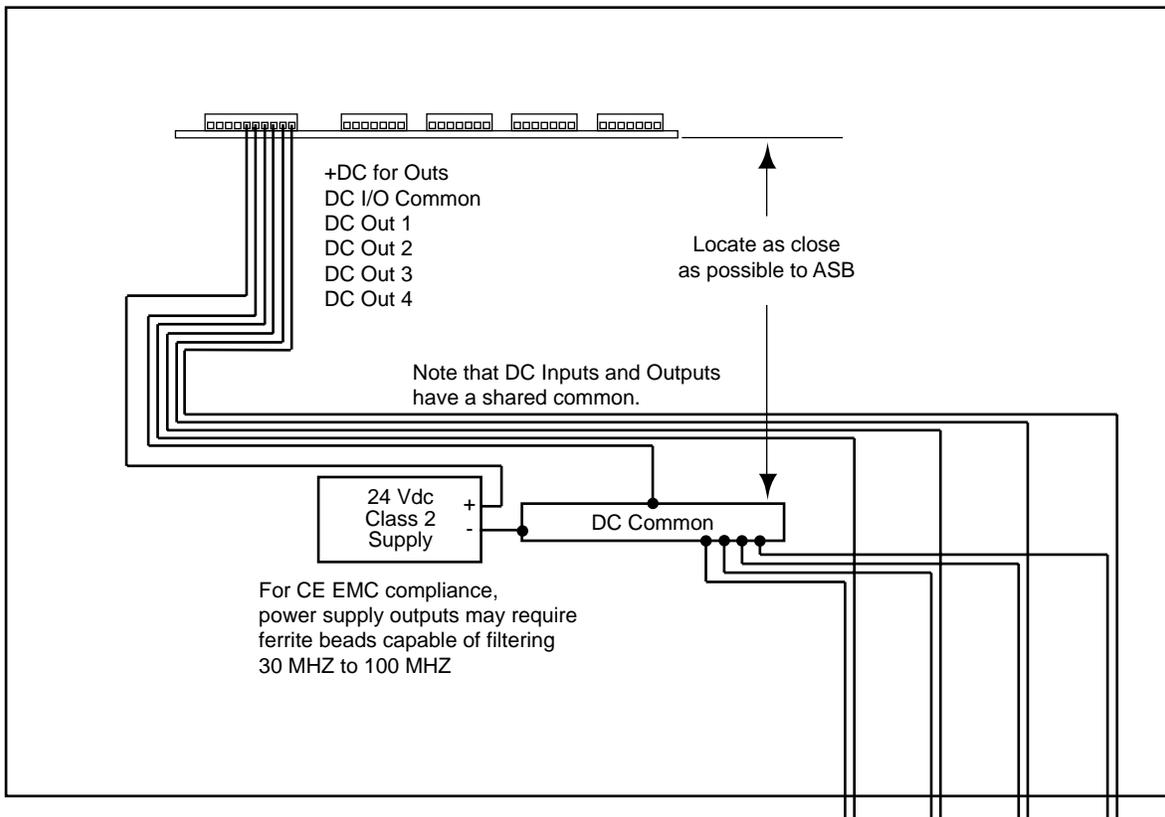


Figure 16. Wiring High Speed Analog Card DC Outputs

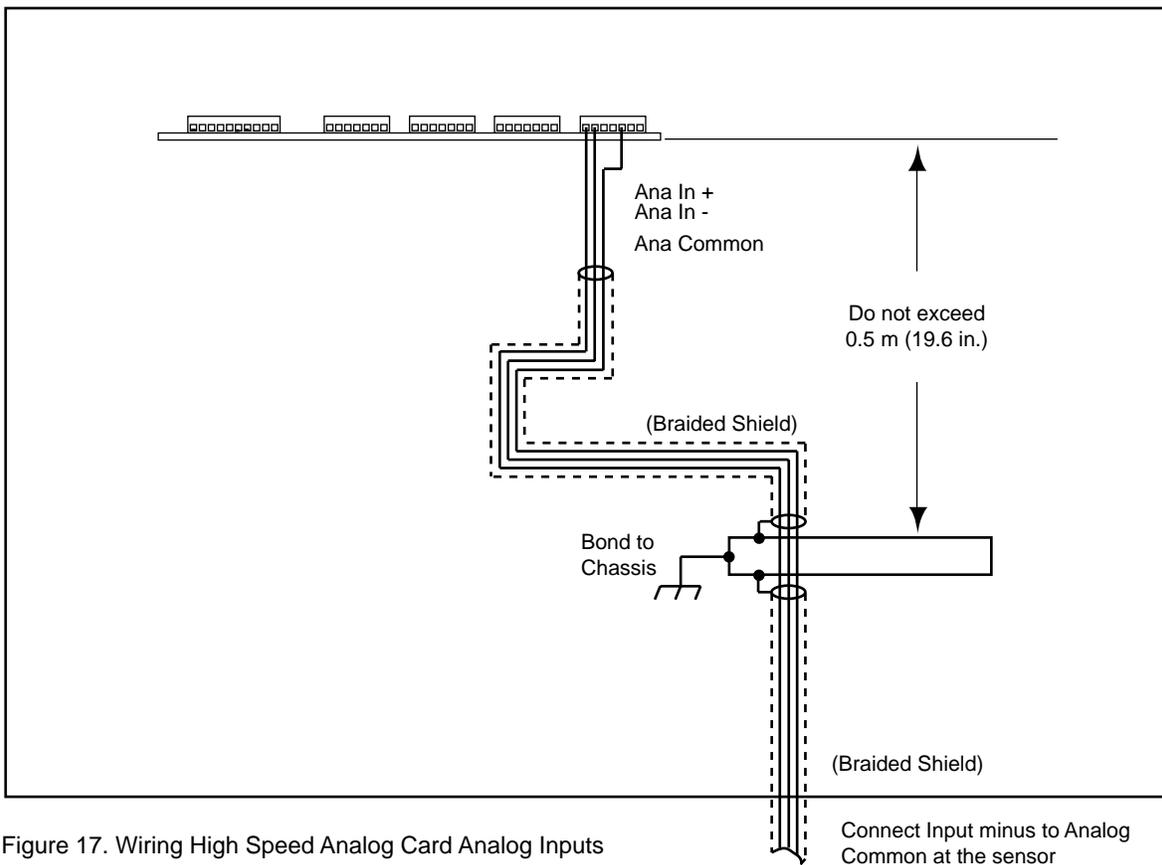


Figure 17. Wiring High Speed Analog Card Analog Inputs

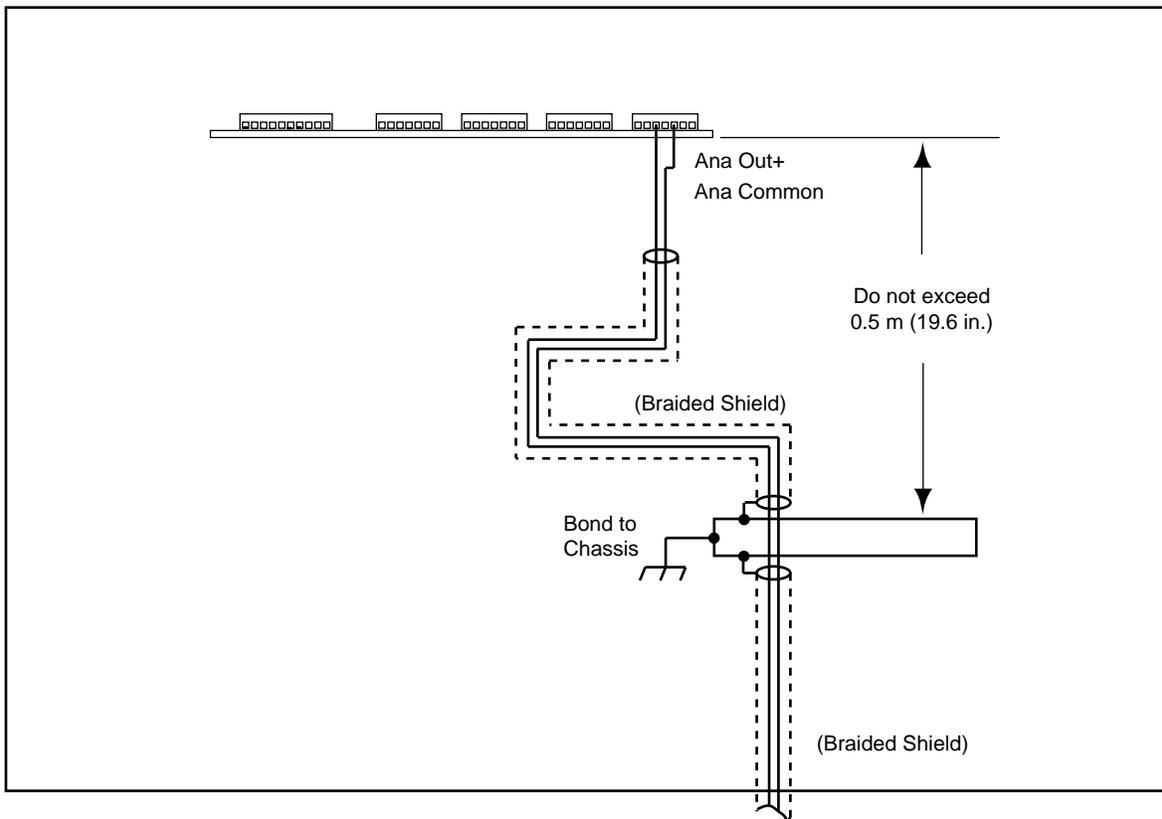


Figure 18. Wiring High Speed Analog Card Analog Outputs

Figure 19. High Speed Analog Sensor Wiring

- Notes:**
1. Excitation voltage from the parison card is limited to +10 Vdc @ 20 mA.
 2. All shields must be connected directly to panel earth ground at one end only.
 3. Input minus (-) must be connected to Analog Common at the sensing device - NOT at the parison card.

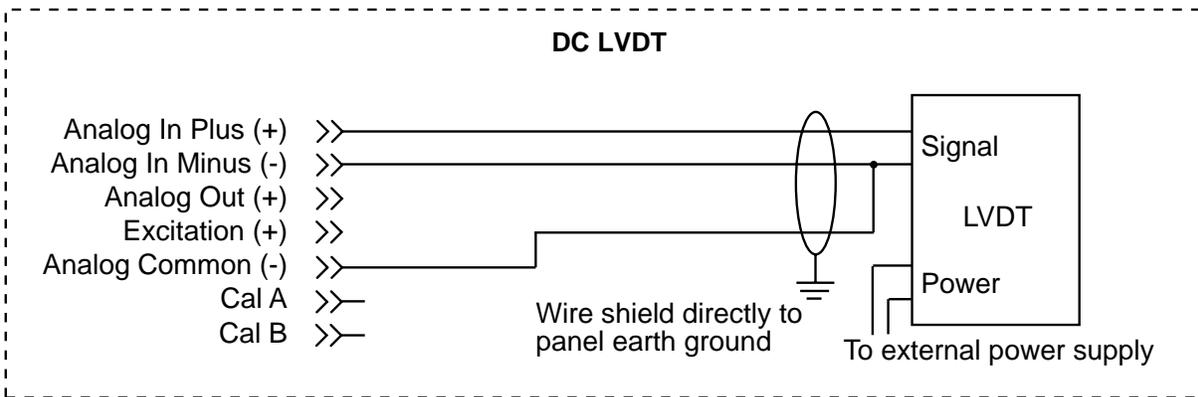
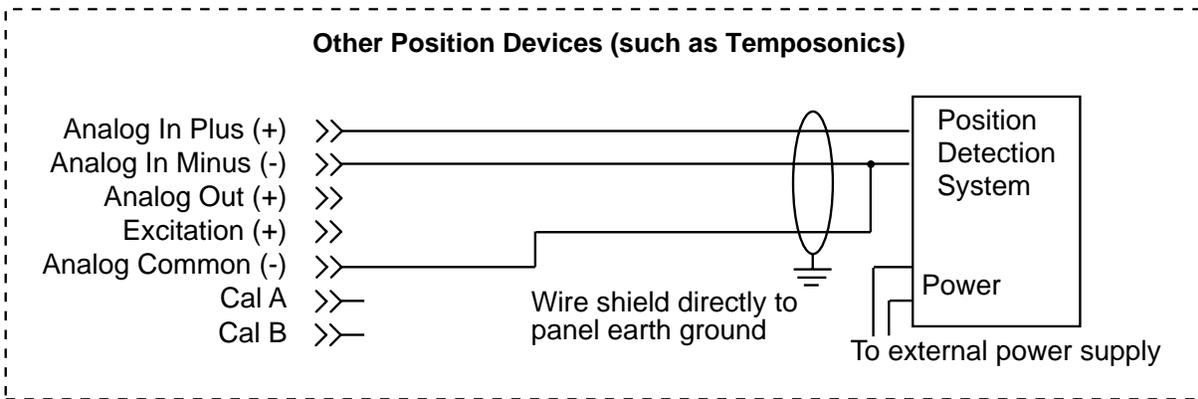
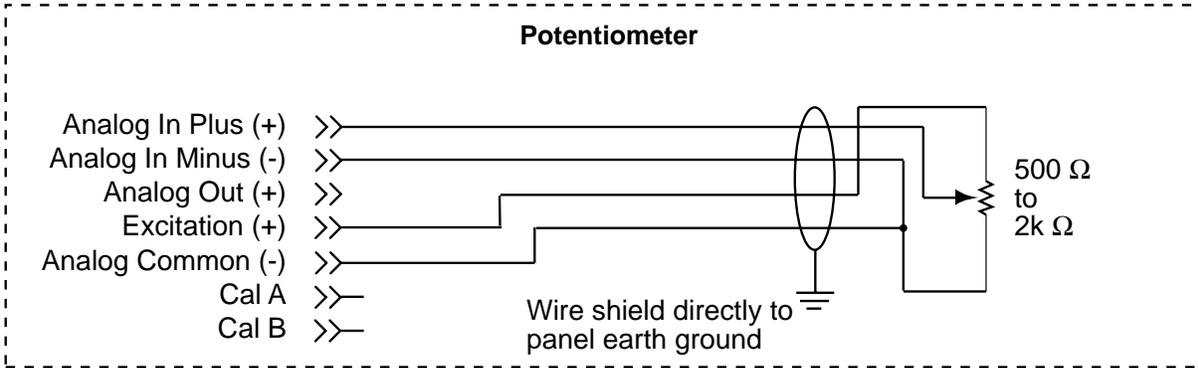
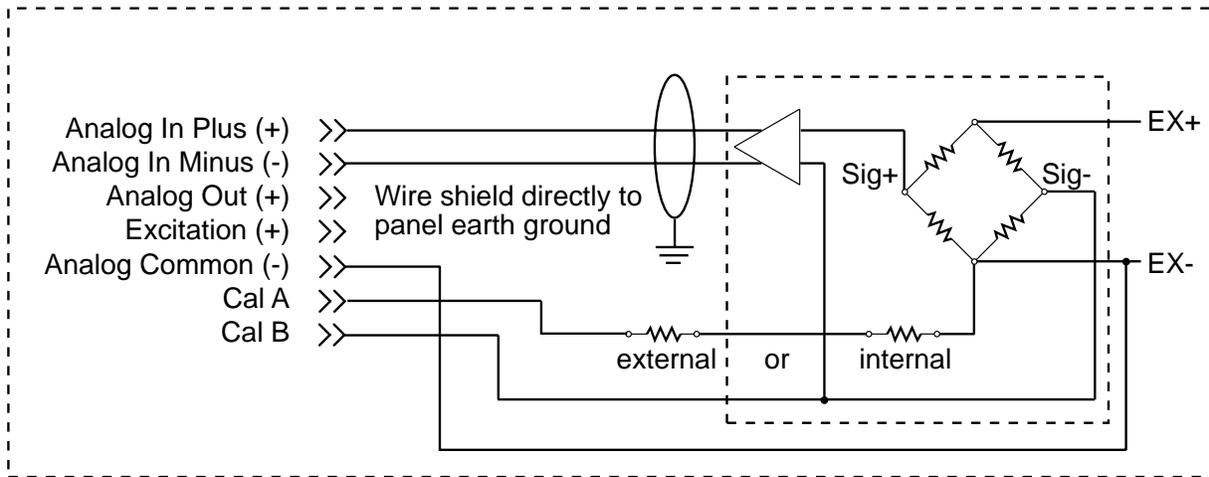


Figure 20. High Speed Analog Card Pressure Transducer Wiring



- Notes:**
1. High level excitation is from an external regulated power supply.
 2. If the transducer does not have a built-in calibration resistor, insert resistor as shown between EX(-) and CAL terminal.
 3. If resistor is not built-in, use value specified by manufacturer.

Figure 21. High Speed Analog Card DC Input and Output Wiring

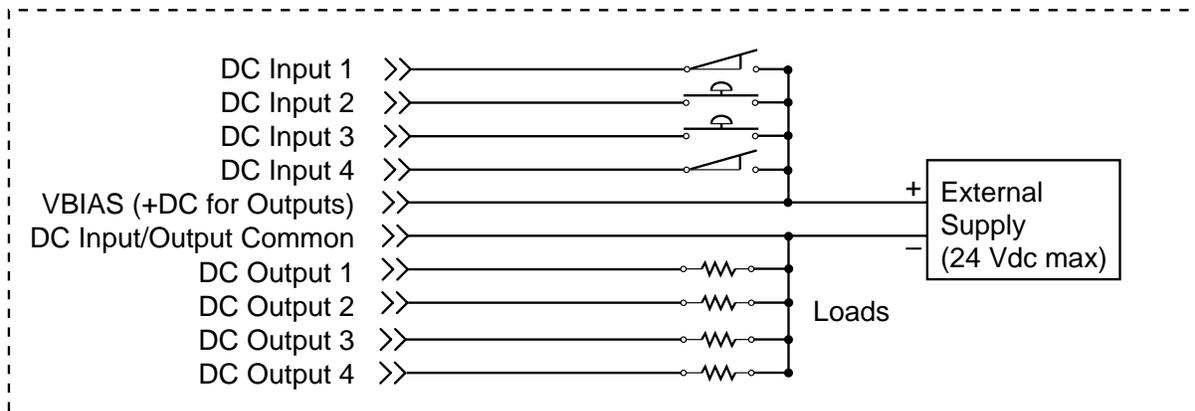
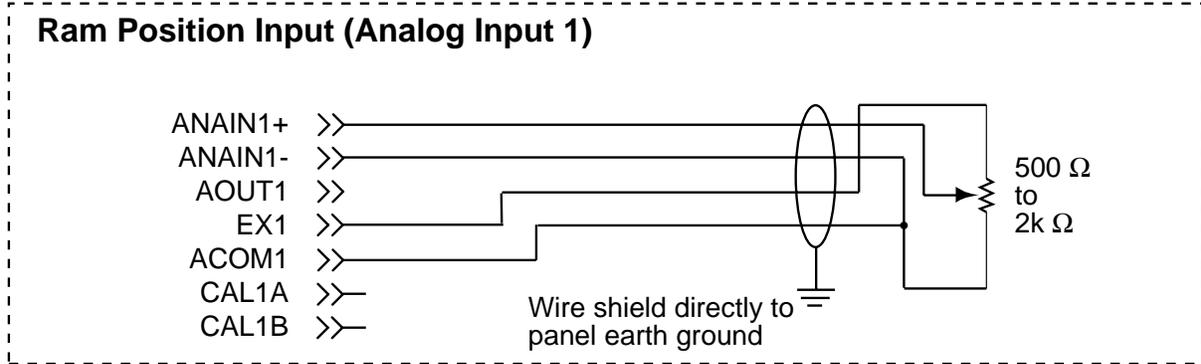
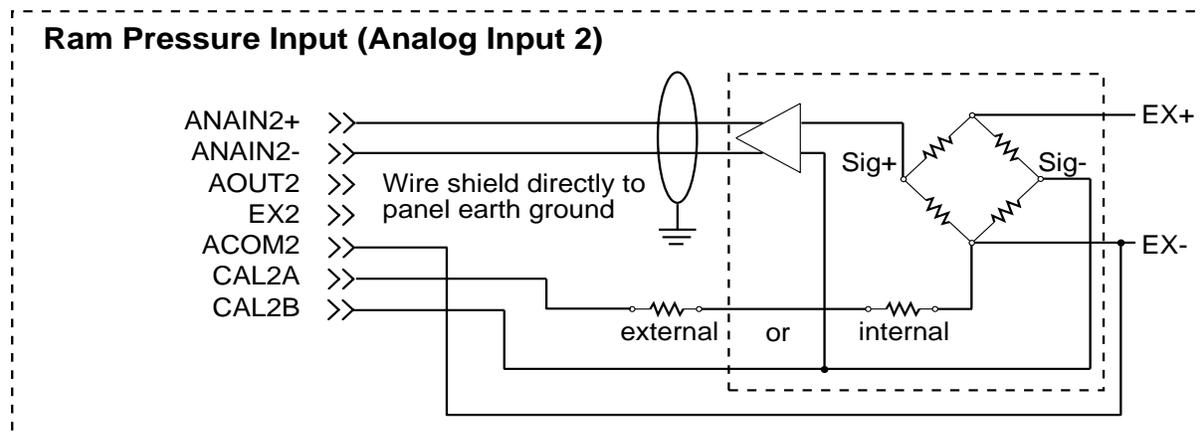
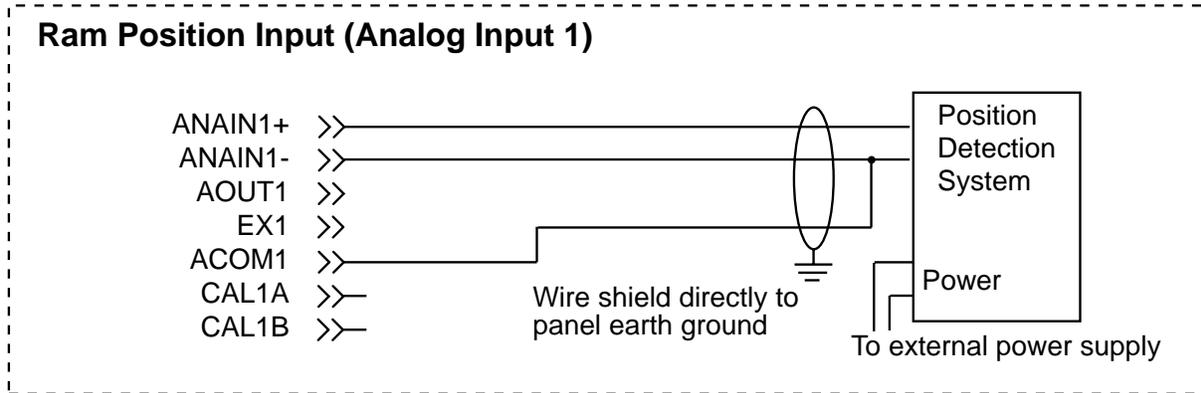


Figure XX. Sensor Wiring for Injection Control

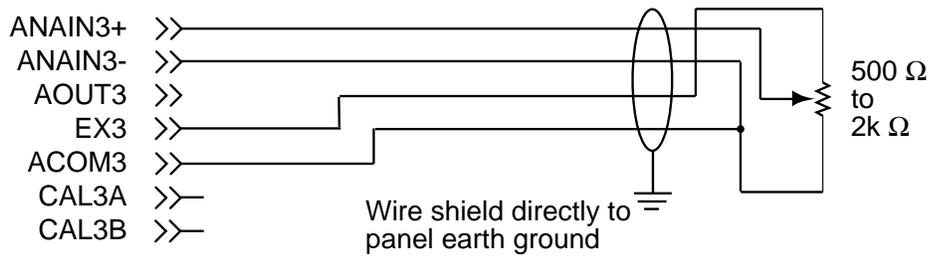
- Notes:**
1. Excitation voltage from the card is limited to +10 Vdc @ 20 mA.
 2. All shields must be connected directly to panel earth ground at one end only.
 3. Input minus (-) must be connected to Analog Common at the sensing device - NOT at the card.



OR

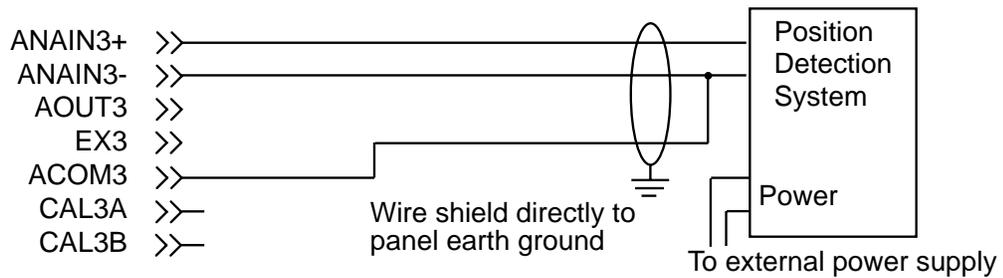


Clamp Position Input (Analog Input 3)

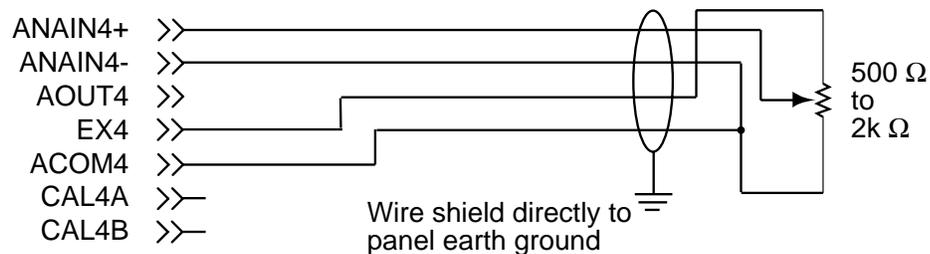


OR

Clamp Position Input (Analog Input 3)

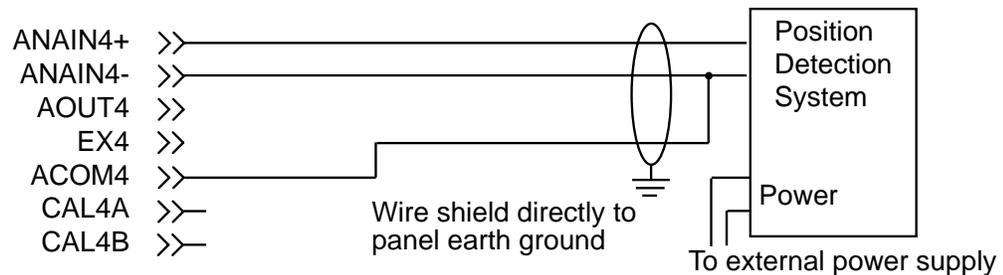


Ejector Position Input (Analog Input 4)

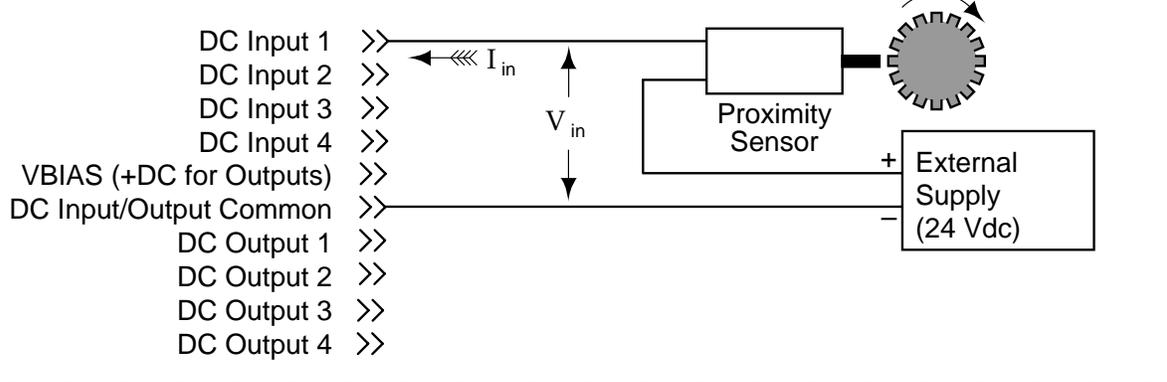


OR

Ejector Position Input (Analog Input 4)



Tachometer Input



A DC input used as a tachometer input will accept up to 40 Vdc at 1Khz. The measuring device typically puts out a series of pulses proportional to the shaft RPM to which it is mounted.

Logic levels for the input are $10 \text{ Vdc} < V_{\text{high}}$ and $V_{\text{low}} < 5 \text{ Vdc}$.

When used as a tach input, the minimum ON voltage should be increased to at least 12 Vdc. The driving device must be capable of sourcing 10mA to the input. The ON and OFF times for the input pulse must EACH be greater than 400ns (a waveform of 100ns ON and 900ns OFF even though it is 1KHz does NOT meet the specification). The signal level for the logic high must be at or above the required level for the minimum required time in order to be counted.

$$V_{\text{in}} > 10\text{V} = \text{ON}$$

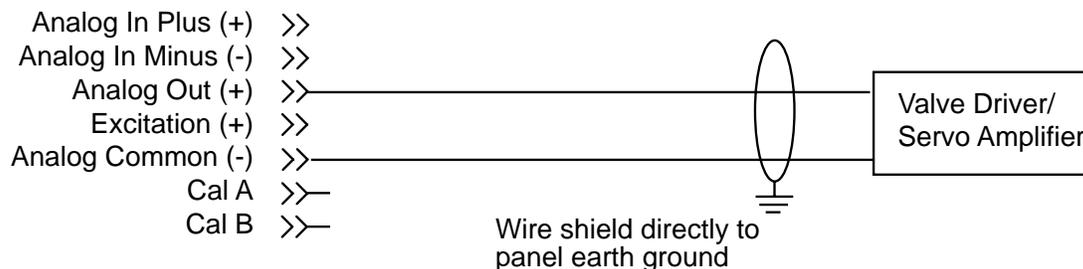
$$V_{\text{in}} < 5\text{V} = \text{OFF}$$

$$I_{\text{in on}} = \sim 10\text{mA}$$

$$t_{\text{on min}} = 400\text{ns}$$

$$t_{\text{off min}} = 400\text{ns}$$

Analog Outputs



Analog Outputs can be either 0 to -10 Vdc or 0 to +10 Vdc (by Injection Control Relay – see Programming and Setup).

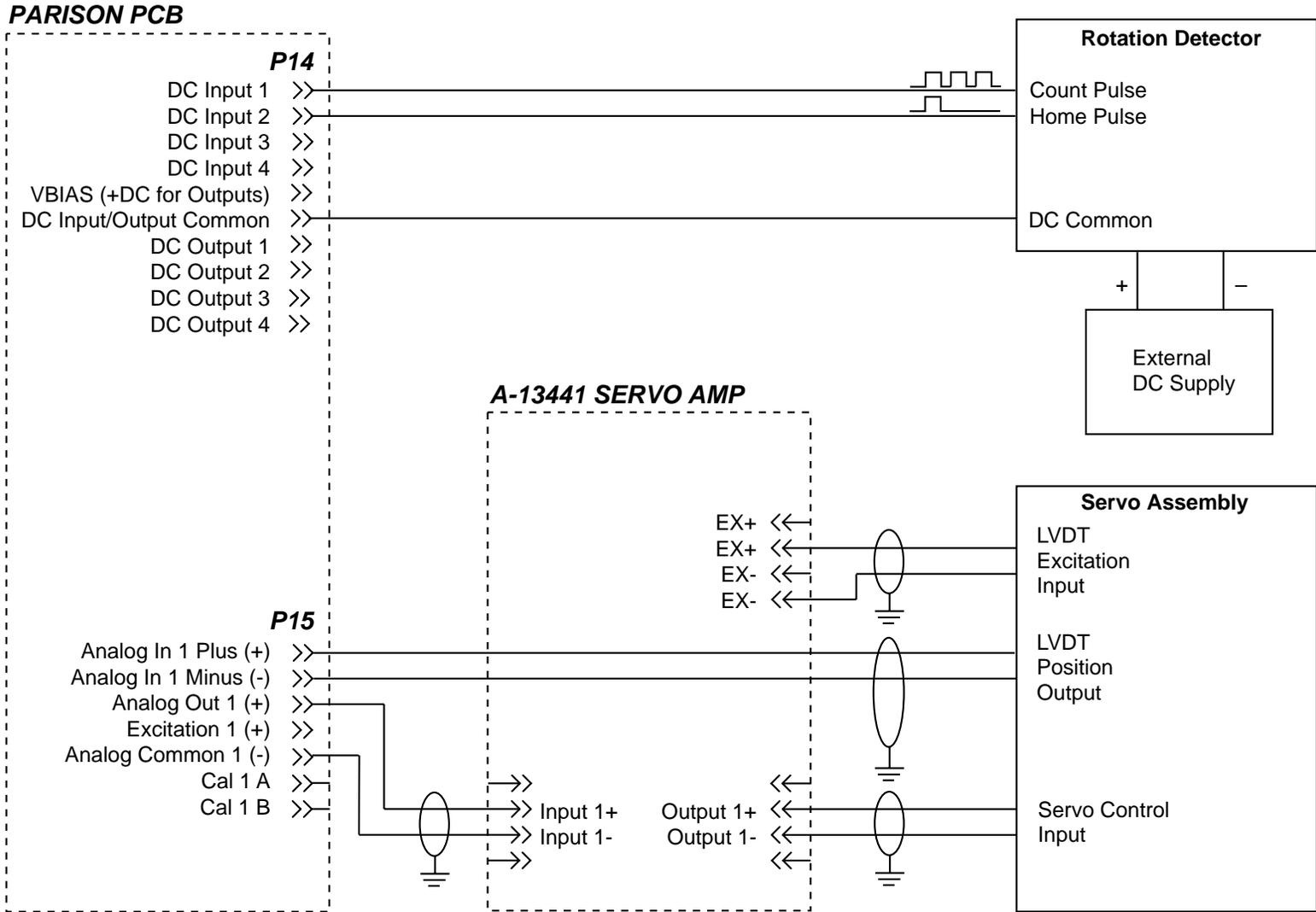


Figure 22. One-Head Time-Based Machine with B-C Servo Amp

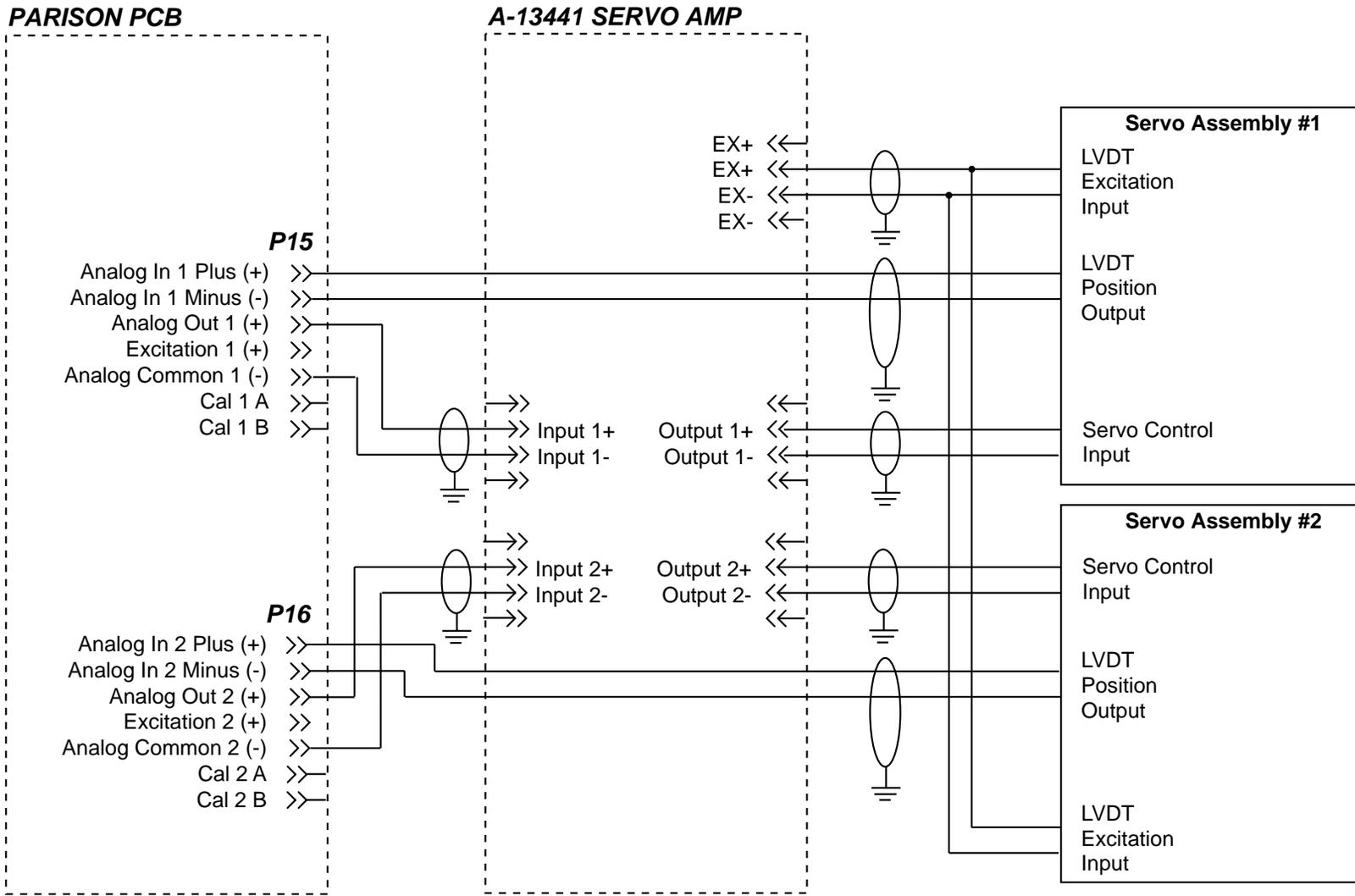


Figure 23. Two-Head Time-Based Machine with B-C Servo Amp

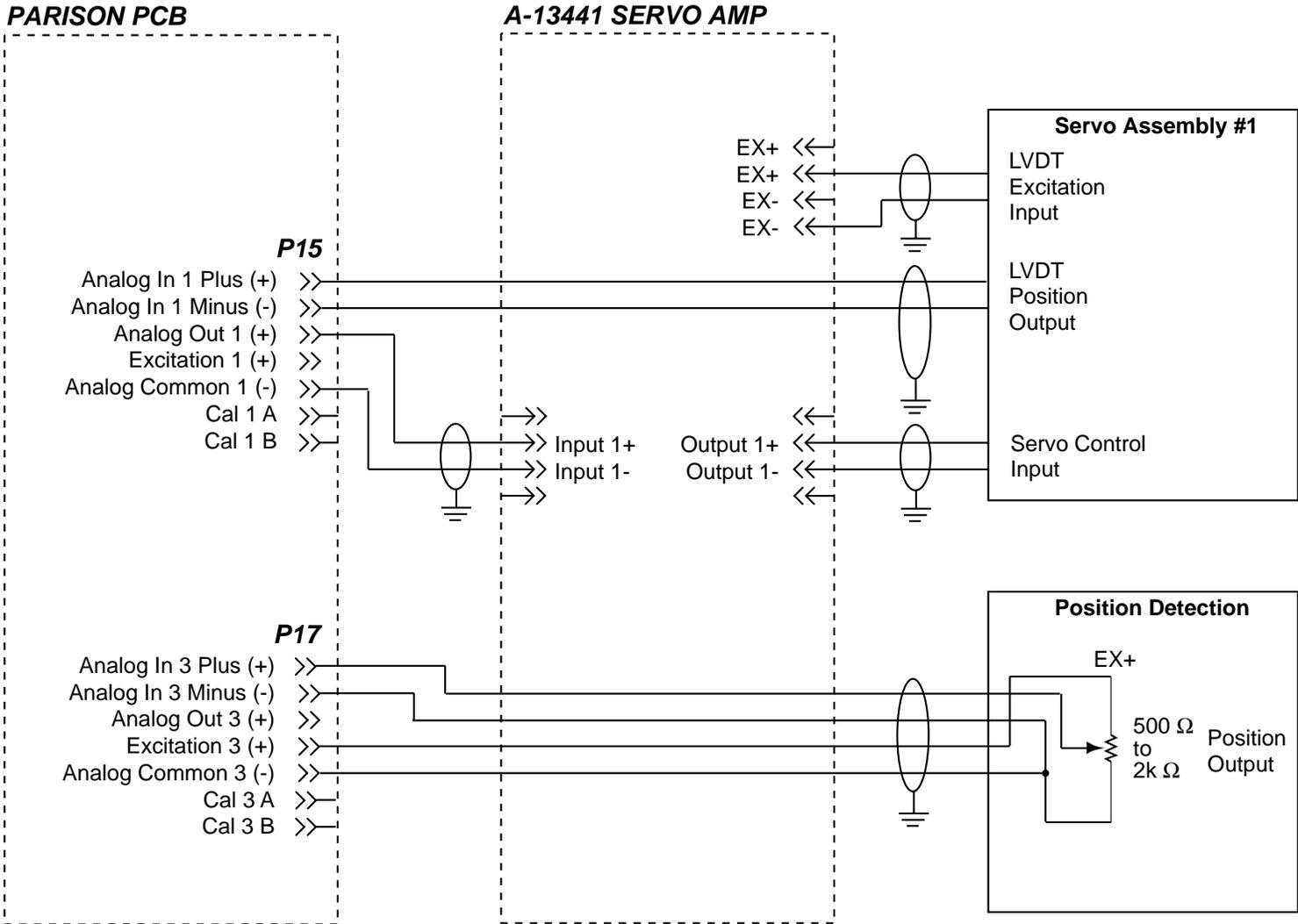


Figure 24. Two-Head Position-Based Machine with B-C Servo Amp

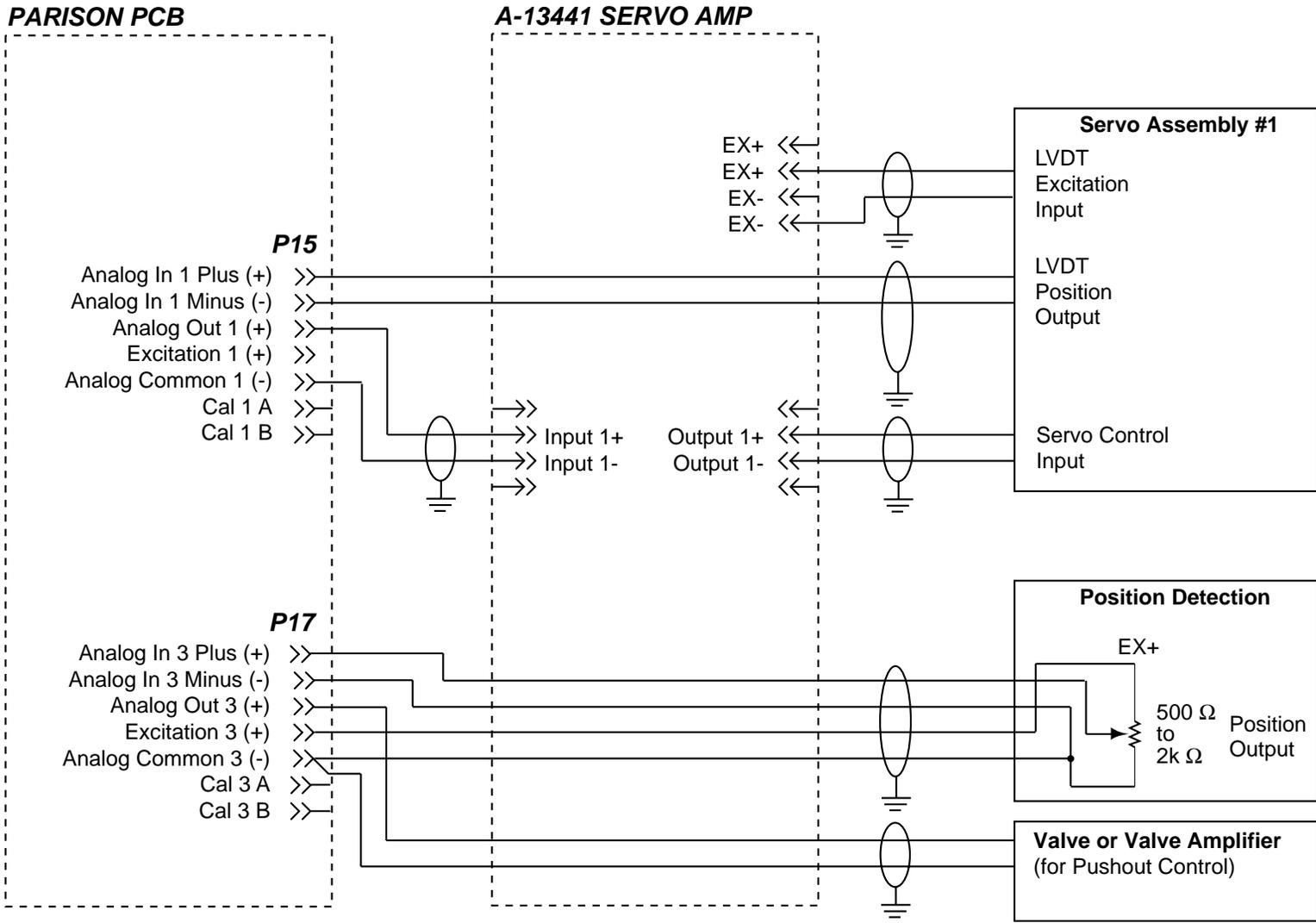


Figure 25. Two-Head Position-Based Machine with Pushout and B-C Servo Amp

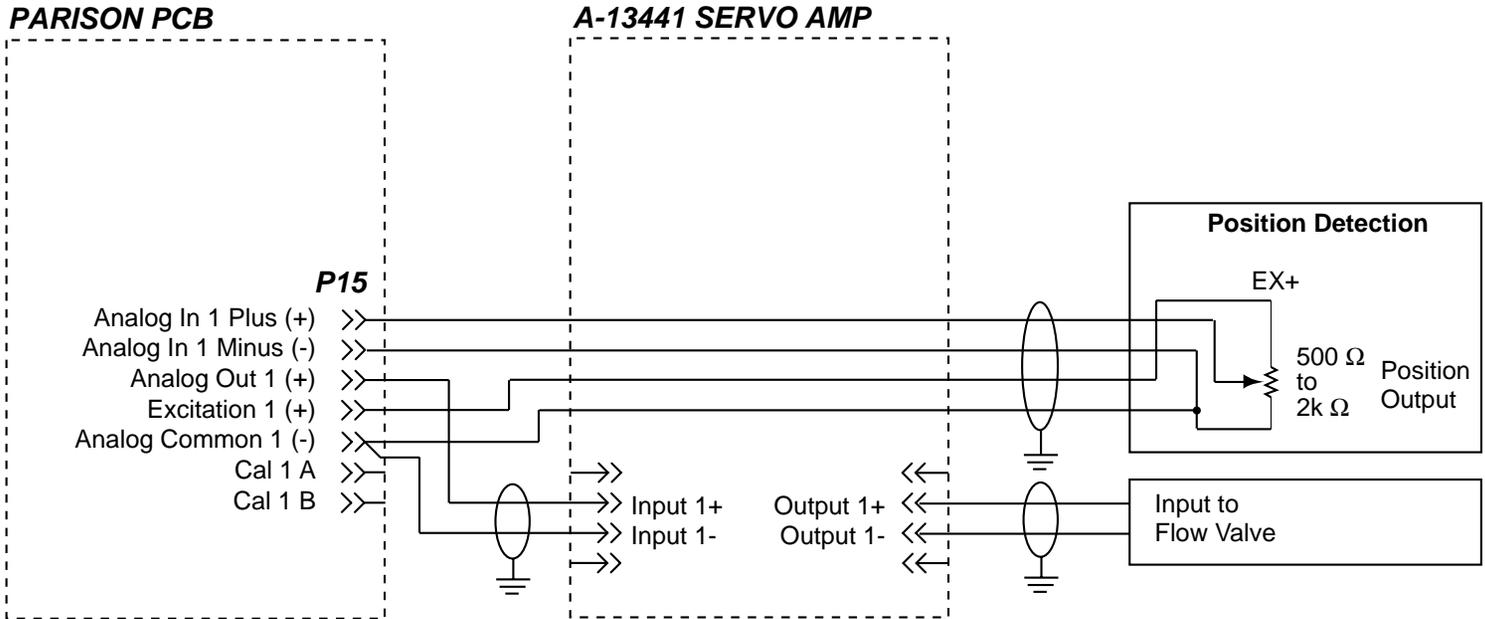


Figure 26. Accumulator Machine (Velocity Control) with B-C Servo Amp

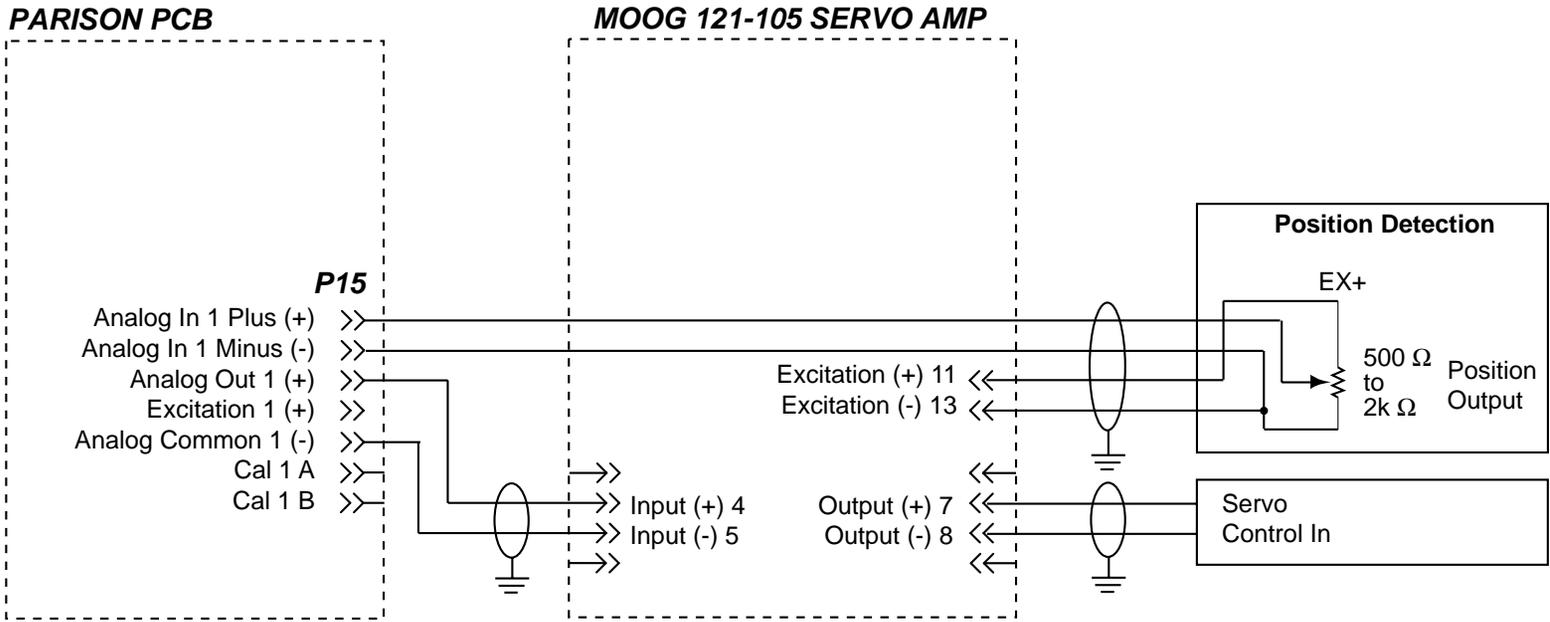
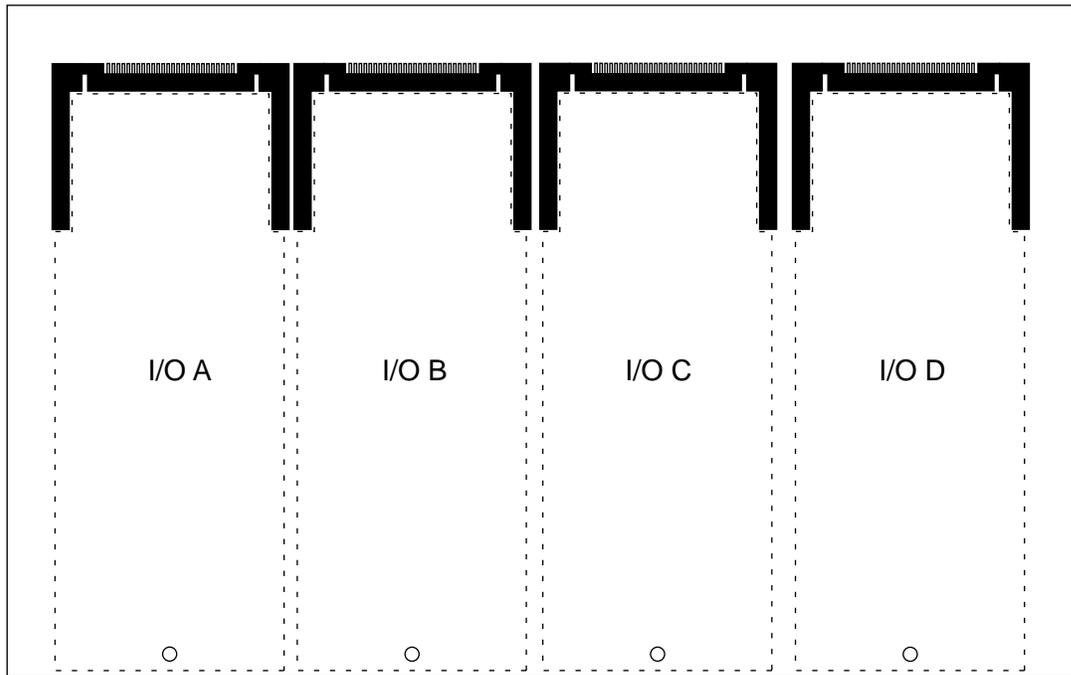


Figure 27. Two-Head Position-Based Machine with Moog Servo Amp

5. Using the 4-Slot Carrier Board

5.1 Introduction

The 4-Slot Carrier Board is designed to hold a variety of optional Input/Output boards. Install all digital I/O first, starting in Slot A, followed by Strain Gauge inputs (if any), followed by communications boards (if any). Refer to the following sections for information on specific I/O boards.



D.1



WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

Figure 28. Four Slot Carrier Board A-60142-xx0

5.2 Wiring the Digital I/O Boards

5.2.1 Introduction

Carrier boards can be ordered with up to 4 input/output daughterboards. Each input/output daughterboard consists of 2 groups of four I/O points, each group powered by its own V+.

Terminal "V1-4" sources outputs for the first group (I/O-1 through I/O4) and terminal "V5-8" sources outputs for the second group (I/O5 through I/O8).

Inputs and outputs can be mixed in a group, however, if power (V1-4, V5-8) is removed from the output circuits in a mixed group, it **MUST** also be **REMOVED** from the inputs of that group. Failure to remove power from the inputs will result in the output circuits being sourced from any input in that group that happens to be ON.

Power must come from a Class 2 power supply (the acceptable voltage range is 12 Vdc to 32 Vdc). Outputs are rated for 2 Amp loads at 24 Vdc; maximum leakage current is 1 mA. Inputs represent a 5 mA load, with a guaranteed turn on voltage of 10 Vdc and a guaranteed turn off voltage of 5 Vdc.

5.2.2 Specifications

Power Supply

Power must come from a Class 2 power supply, 12 to 32 Vdc.

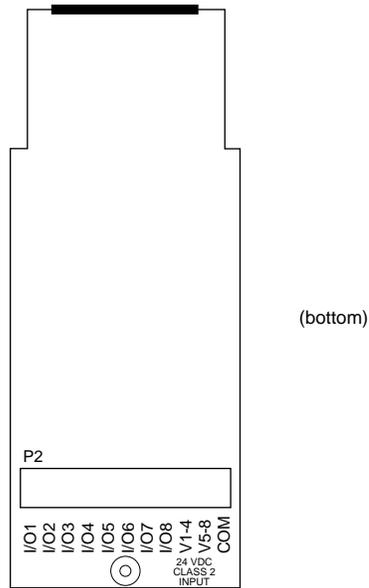
Outputs

Outputs are rated for 2 Amp loads at 24 Vdc. Maximum leakage current is 1 mA. At 55°C ambient and 24 Vdc, these outputs **MUST** be limited to 2 Amps maximum per output, 10 Amps maximum per card and 40 Amps maximum per ASB.

Inputs

Inputs represent a 5 mA load, with a guaranteed turn on voltage of 10 Vdc and a guaranteed turn off voltage of 5 Vdc.

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.



| P2 | |
|------------------|--------------|
| Pin Number | Assignment |
| 1 | I/O1 |
| 2 | I/O2 |
| 3 | I/O3 |
| 4 | I/O4 |
| 5 | I/O5 |
| 6 | I/O6 |
| 7 | I/O7 |
| 8 | I/O8 |
| 9 | V1-4 |
| 10 | V5-8 |
| 11 | COM |
| Mating Connector | E24-1134-011 |

D.1



WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

Figure 29. 8 Input/Output Digital I/O Card A-60138-xx0

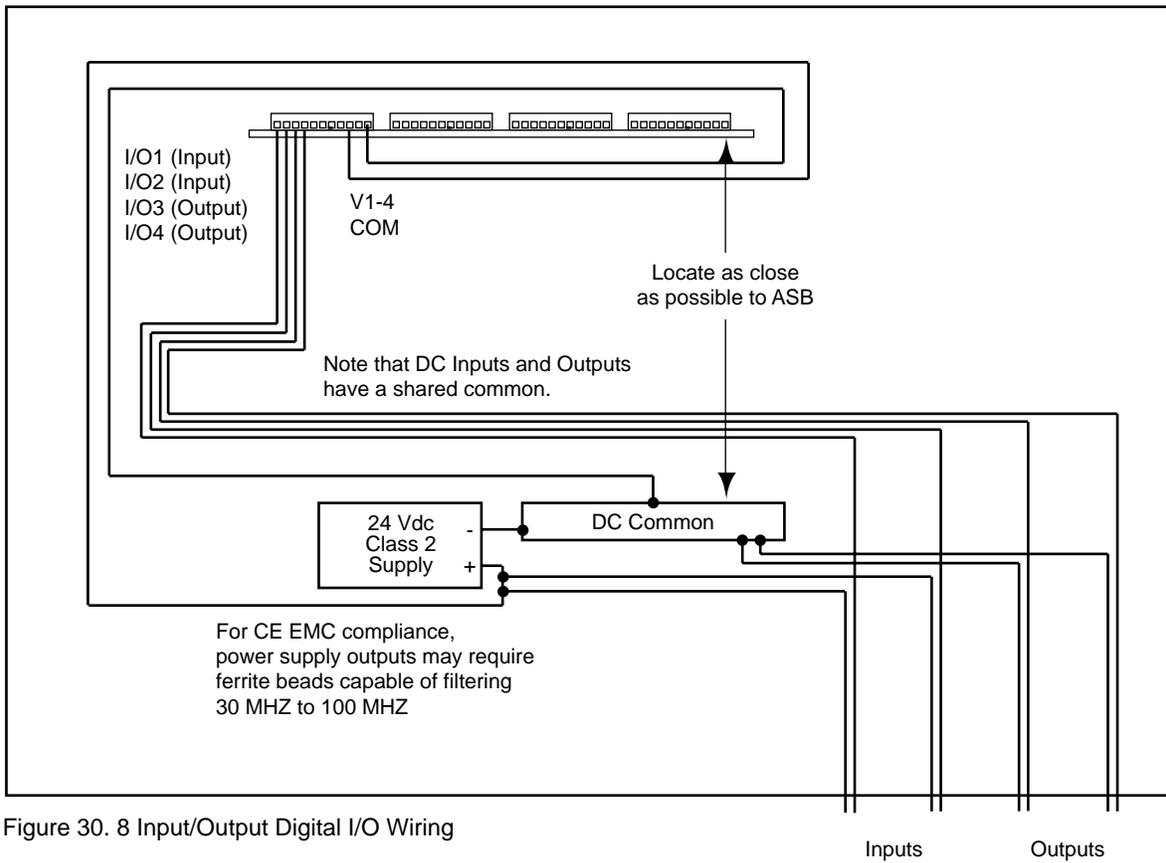
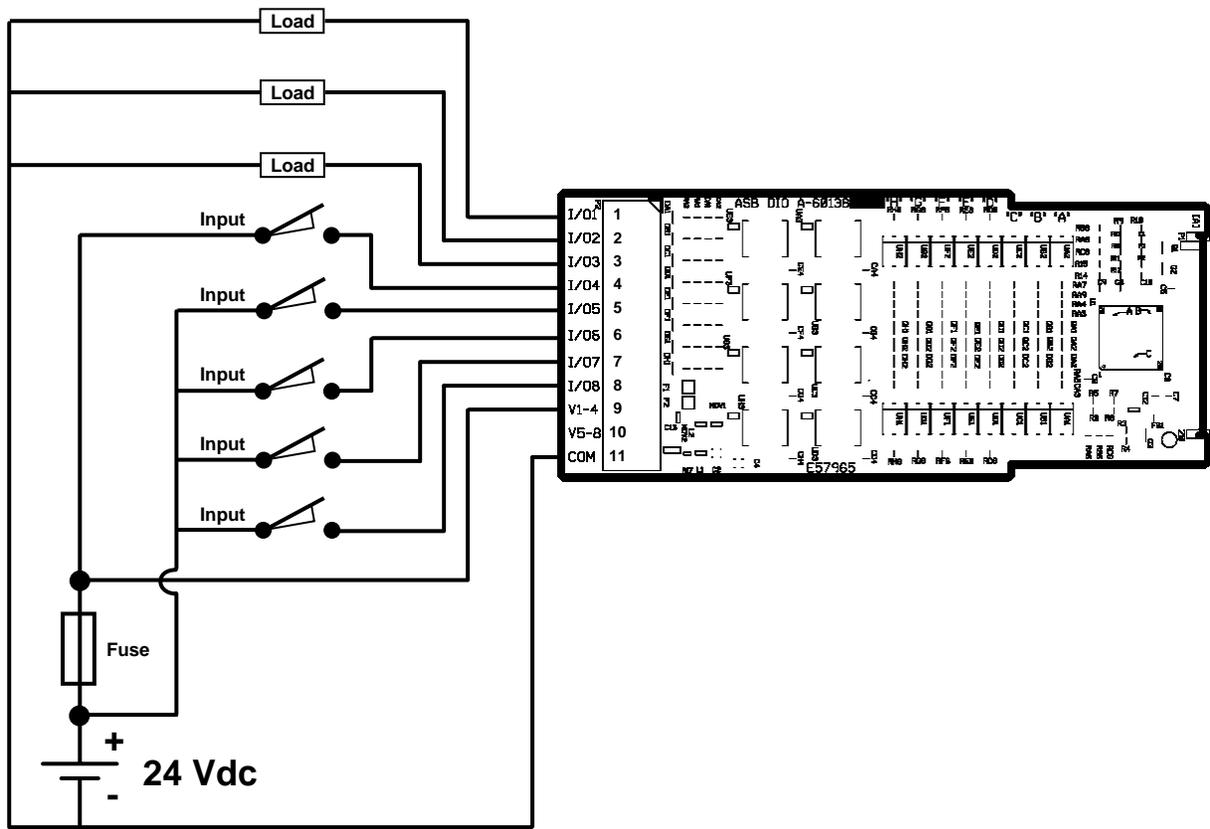


Figure 30. 8 Input/Output Digital I/O Wiring



1. Each card consists of two groups of four I/O points, each group powered by its own V+.
2. Each group of 4 output circuits is fused at 15 Amps on board with a surface mount fuse (NOT field replaceable). Each output circuit is thermally and over-current protected. Outputs are rated at 2 Amps each. Output groups need to be externally fused. The size of the fuse must be determined based on actual load usage, power supply and wire size. Each group of 4 output circuits is rated at a maximum of 8 Amps.
3. V1-4 sources outputs for the first group, Terminals 1 thru 4. V5-8 sources outputs for the second group, Terminals 5 thru 8.
4. Inputs and outputs can be mixed in a group, however, if power (V1-4, V5-8) is removed from the output circuits in a mixed group, it MUST also be REMOVED from the inputs of that group. Failure to remove power from the inputs will result in the output circuits being sourced from any input in that group that happens to be ON.
5. Power must come from a Class 2 power supply (the acceptable voltage range is 12 Vdc to 32 Vdc). Outputs are rated for 2 Amp loads at 24 Vdc; maximum leakage current is 1 mA. Inputs represent a 5 mA load, with a guaranteed turn on voltage of 10 Vdc and a guaranteed turn off voltage of 5 Vdc.
6. At 55°C ambient and 24 Vdc, these outputs MUST be limited to 2 Amps maximum per output, 10 Amps maximum per card and 40 Amps maximum per ASB.

Figure 31. 8 Input/Output Sample Wiring

5.3 Wiring the 2 Channel Analog Input Board

5.3.1 Introduction

Carrier boards can be ordered with up to two 2 Channel Analog Input boards. These boards are primarily meant for strain gauge pressure inputs. Each daughterboard has 2 channels of pressure transducer input. Calibration relay contacts and excitation voltage is provided. A thermocouple input (with cold junction temperature sensing) can be used in place of the transducer input, if desired. Each channel also includes one voltage or current input.

5.3.2 Specifications

Resolution: 16 bits

Accuracy: 0.1%

Stability: 10 ppm

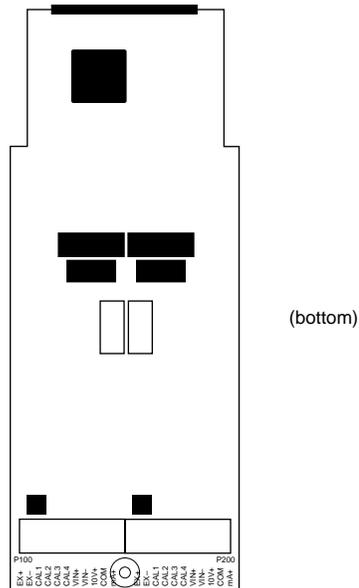
Sampling Rate: 20 Samples per second

Input Types:

Pressure Transducer, 2mV/Volt or 4mV/Volt sensitivity
Cold Junction Temperature Voltage
0 to 10 Vdc
4 to 20 mAdc

Isolation: 500 Volts channel to channel
500 Volts channel to digital common

| |
|---|
| Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors. |
|---|



| P100 | |
|------------------|---|
| Pin Number | Assignment |
| 1 | EX+ for Channel 1 |
| 2 | EX- for Channel 1 |
| 3 | CAL1 (Sensor Cal Lead if External Cal Resistor) |
| 4 | CAL2 (External Cal Resistor) |
| 5 | CAL3 (External Cal Resistor, Cal Relay Contact) |
| 6 | CAL4 (Cal Relay Contact) |
| 7 | VIN+ for Pressure Input or T/C+ |
| 8 | VIN- for Pressure Input or T/C- |
| 9 | 0 to 10 Vdc Input + |
| 10 | COM |
| 11 | 4 to 20 mA Input + |
| Mating Connector | E24-1519-011 |

| P200 | |
|------------------|---|
| Pin Number | Assignment |
| 1 | EX+ for Channel 2 |
| 2 | EX- for Channel 2 |
| 3 | CAL1 (Sensor Cal Lead if External Cal Resistor) |
| 4 | CAL2 (External Cal Resistor) |
| 5 | CAL3 (External Cal Resistor, Cal Relay Contact) |
| 6 | CAL4 (Cal Relay Contact) |
| 7 | VIN+ for Pressure Input or T/C+ |
| 8 | VIN- for Pressure Input or T/C- |
| 9 | 0 to 10 Vdc Input + |
| 10 | COM |
| 11 | 4 to 20 mA Input + |
| Mating Connector | E24-1519-011 |

D.1



WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

Figure 32. Two Channel Analog Input Card A-60148

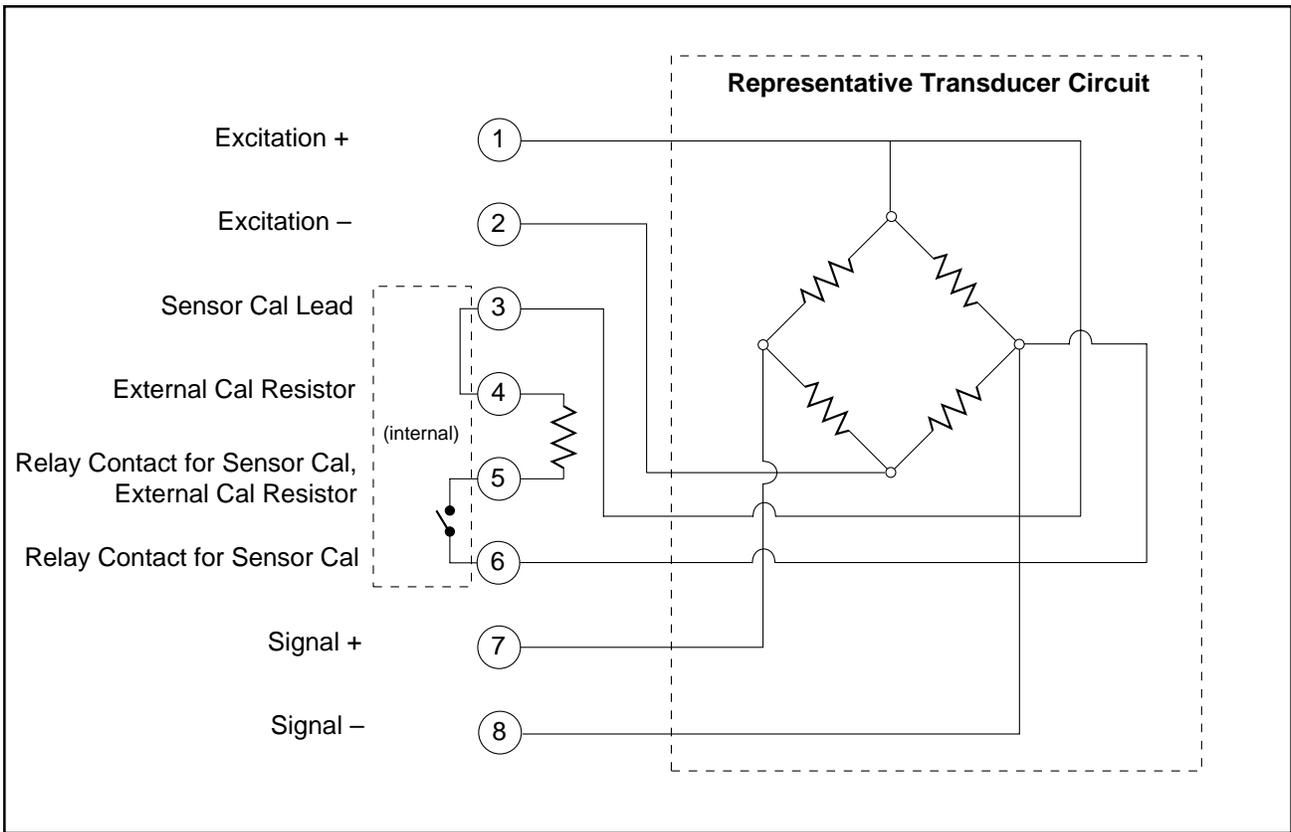


Figure 33. Wiring for External Cal Resistor

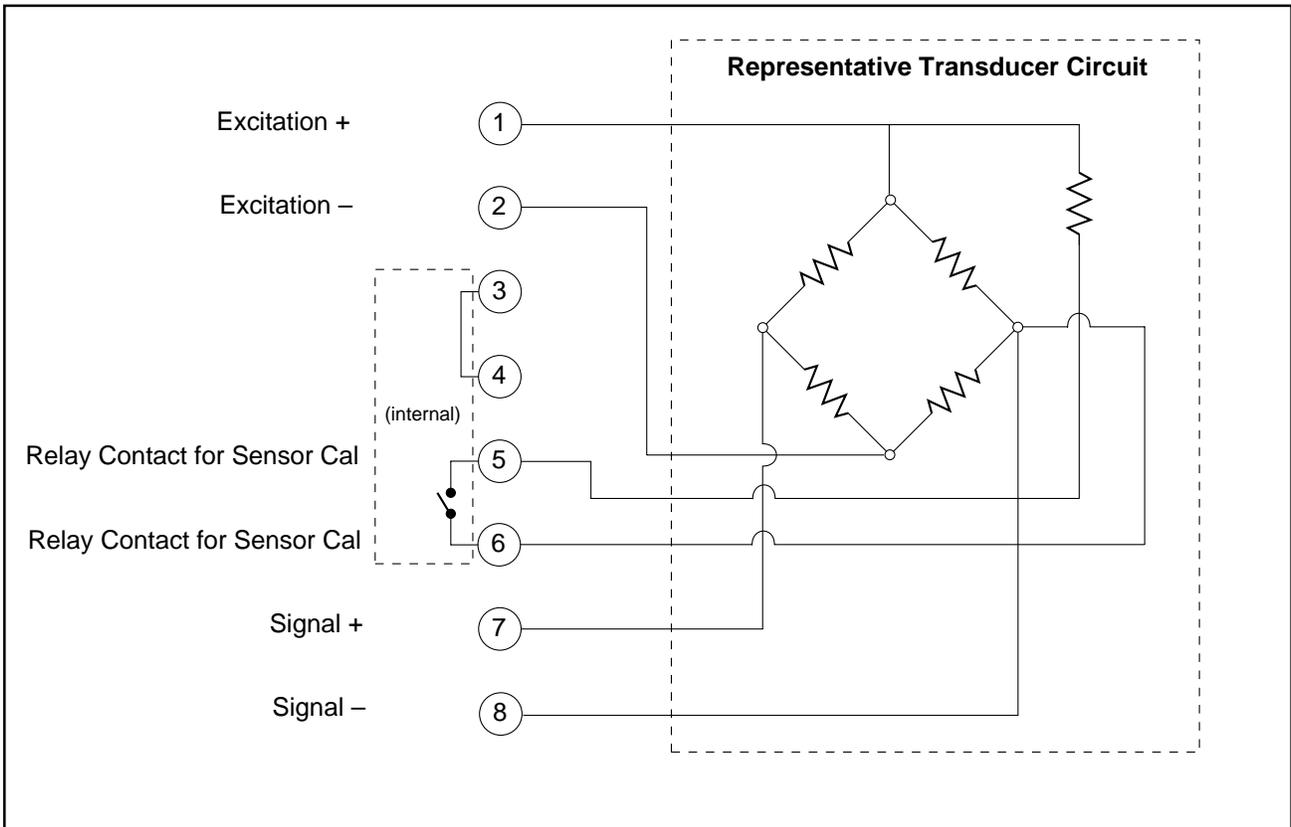


Figure 34. Wiring for Internal Cal Resistor

5.4 Wiring the MACO-NET Communications Board

5.4.1 Introduction

The MACO-NET Communications board is used only for communicating with a standard (non-PC) operator station. Only one MACO-NET board is required per system and it should be installed in Node 1 of the system.

If there is a Rack in the system, a Rack should be designated as Node 1 (and the MACO-Net card should reside in Slot C of the 2-Slot carrier board which is part of the Data Handler block of Node 1).

If the system consists of ASBs only, the MACO-Net card should reside in Slot D of the 4-Slot carrier board in Node 1.

All address switches should be in the down (off) position.

Note that the operator station attached to this card will require an external Class 2 supply capable of 15 Vdc, 2 Amps (minimum); 15 Vdc, 3 Amps (recommended).

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

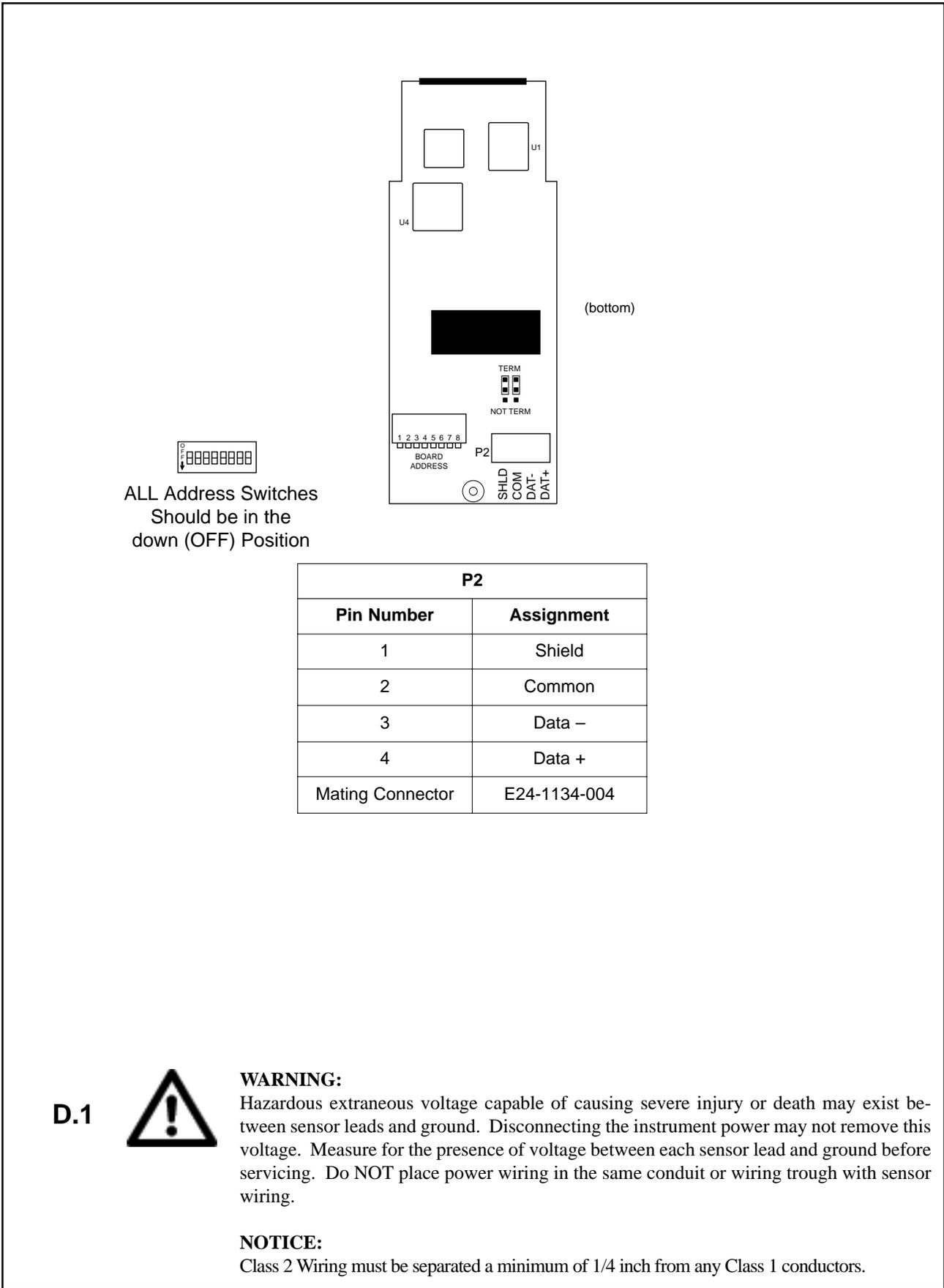


Figure 35. MACO-NET Card A-60187

5.5 Wiring the Encoder Board

5.5.1 Introduction

Each encoder daughterboard contains circuitry for two incremental quadrature encoders. A customer-supplied 24 Vdc is required for the board. Two isolated 5 Vdc supplies are then provided by the board to power the encoders.

The inputs for the respective phase, home and fault signals are RS-422 compliant for a receiver (R) and cable termination (Rt). Each of the signals (A, /A, B, /B, H, /H) is terminated by a 120 Ohm resistor.

5.5.2 Specifications

Power Supply

(User Supplied): 24 Vdc (18 Vdc to 36 Vdc), 1 Amp minimum, Class 2

Termination (Rt): 120 Ohms

Threshold (Vt): ± 200 mV

Common Mode

(Vcm): ± 7 Vdc

Supply Output: 5 Vdc, ± 250 mV @ 200 mA each supply output

For a quadrature encoder, 2 logical signals are required in order to provide phase and directional information. These signals are input to the card as the A, /A, B, /B inputs. Logic signals A and B are out of phase by 90 degrees. The signal levels of A and /A are the logical inverse of one another.

An RS-422 logic signal is represented as the differential between 2 levels. A logical signal is true if level A is greater than level /A and is false when level A is less than level /A. the differential threshold is 200 mV. In other words, for a logical level 1 (ON) to be received, input signal A must be greater than input signal /A by at least 200 mV. Conversely, for a logical 0 (OFF) to be received, input signal A must be less than input signal /A by at least 200 mV. If the input signals are within 200 mv of each other, the logic level is undefined.

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

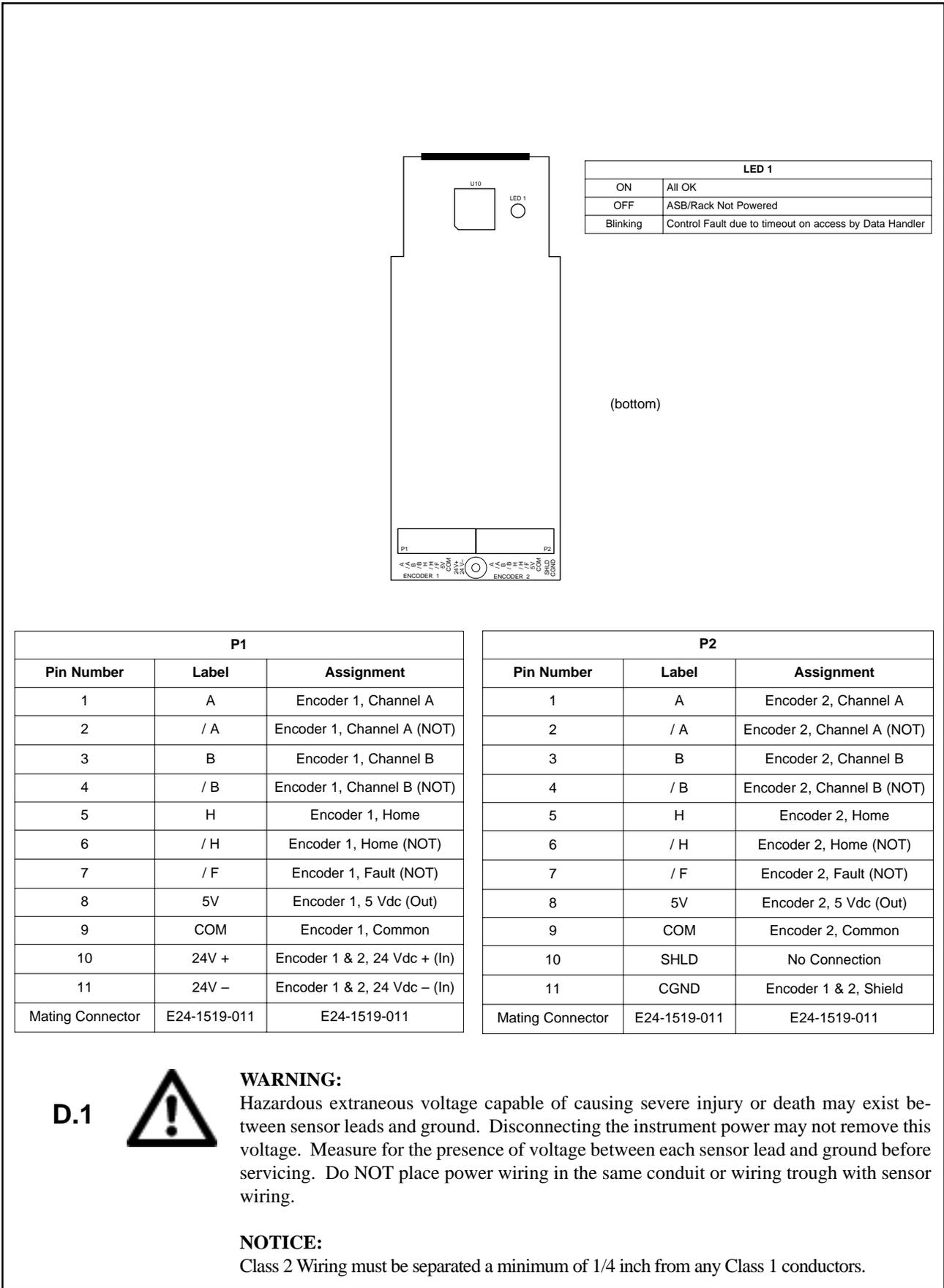


Figure 36. Encoder Card A-60191

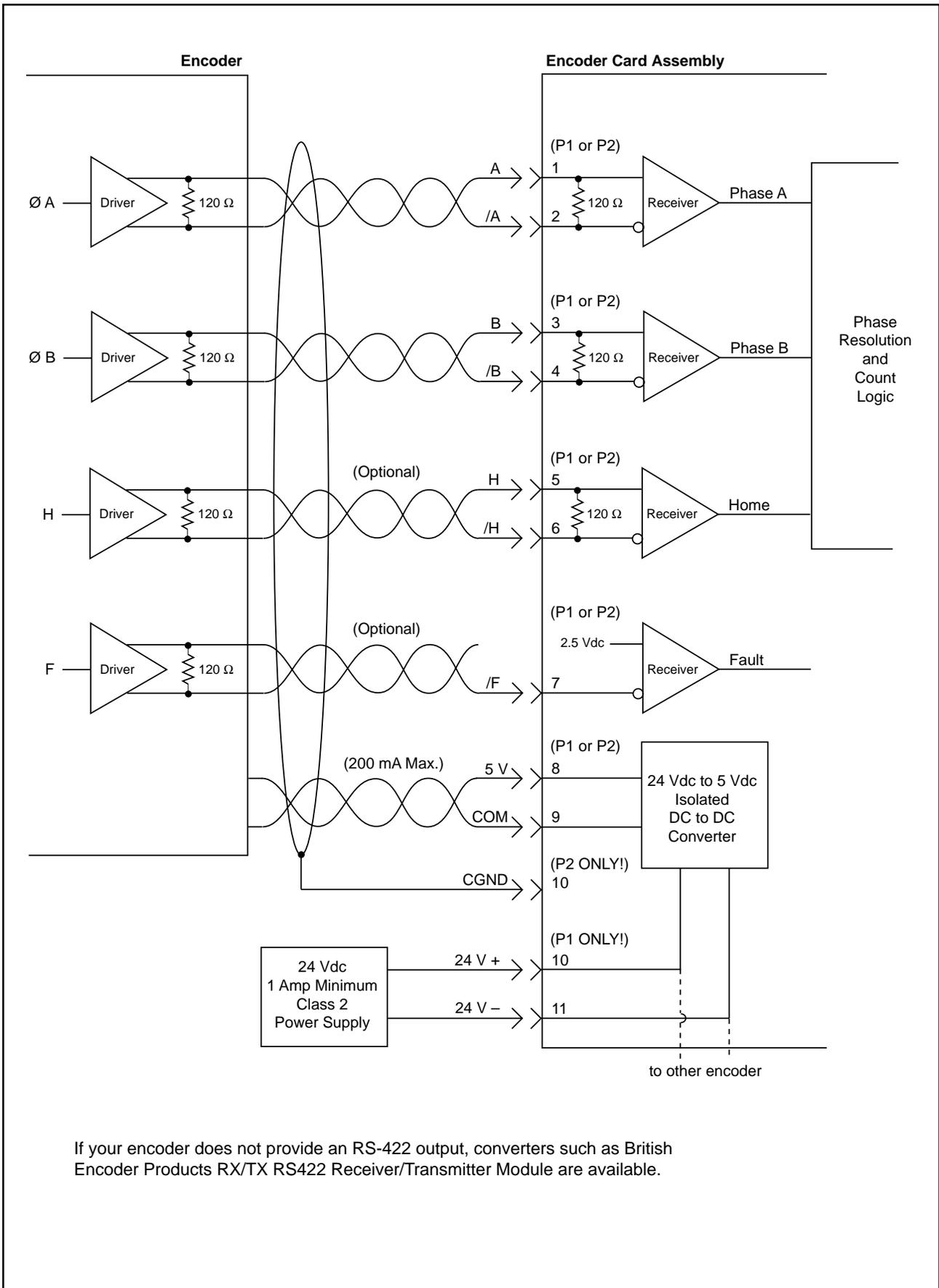


Figure 37. Wiring the Encoder Card

6. Wiring the 32 In/32 Out or 24 In/24 Out Digital I/O Boards

6.1 Introduction

The 32 In/32 Out Digital I/O board is capable of (both) 32 inputs and 32 outputs. Outputs are sourced in groups of 4, with Vcc 1-4 supplying Output 1 through Output 4, Vcc 5-8 supplying Output 5 through 8, etc.

Each output circuit is thermally and over-current protected. Output groups need to be externally fused. The size of the fuse must be determined based on actual load usage, power supply and wire size.

6.2 Specifications

Power Supply

Power must come from a Class 2 power supply, 18 to 32 Vdc.

Outputs

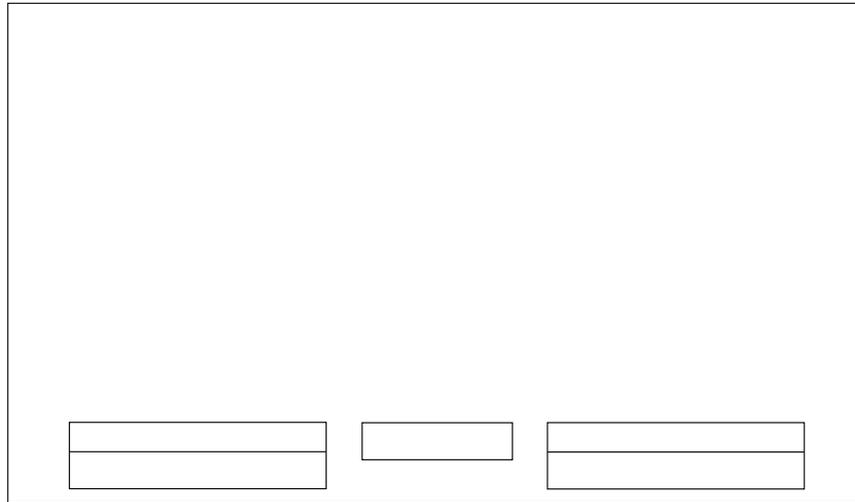
Outputs are rated for 2 Amp loads at 24 Vdc. Maximum leakage current is 1 mA. At 55°C ambient and 24 Vdc, these outputs **MUST** be limited to 2 Amps maximum per output, 8 Amps maximum per group and 64 Amps maximum per card (48 Amps for the 24 In/24 Out version).

Inputs

Inputs represent a 3 mA load, with a guaranteed turn on voltage of 16 Vdc and a guaranteed turn off voltage of 5 Vdc.

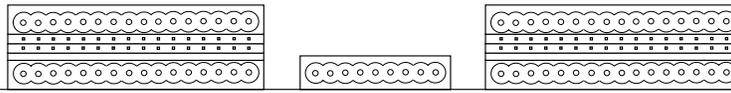
Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

(bottom)



Top Row
 Output 1
 Output 2
 Output 3
 Output 4
 Output 5
 Output 6
 Output 7
 Output 8
 Output 9
 Output 10
 Output 11
 Output 12
 Output 13
 Output 14
 Output 15
 Output 16
 Vcc 1-4
 Vcc 5-8
 Vcc 9-12
 Vcc 13-16
 Vcc 17-20
 Vcc 21-24
 Vcc 25-28
 Vcc 29-32
 Common
 Output 17
 Output 18
 Output 19
 Output 20
 Output 21
 Output 22
 Output 23
 Output 24
 Output 25
 Output 26
 Output 27
 Output 28
 Output 29
 Output 30
 Output 31
 Output 32

Bottom Row
 Input 1
 Input 2
 Input 3
 Input 4
 Input 5
 Input 6
 Input 7
 Input 8
 Input 9
 Input 10
 Input 11
 Input 12
 Input 13
 Input 14
 Input 15
 Input 16
 Input 17
 Input 18
 Input 19
 Input 20
 Input 21
 Input 22
 Input 23
 Input 24
 Input 25
 Input 26
 Input 27
 Input 28
 Input 29
 Input 30
 Input 31
 Input 32



| Pin Number | Upper Connector | Lower Connector |
|------------------|-----------------|-----------------|
| | Assignment | Assignment |
| 1 | Output 1 | Input 1 |
| 2 | Output 2 | Input 2 |
| 3 | Output 3 | Input 3 |
| 4 | Output 4 | Input 4 |
| 5 | Output 5 | Input 5 |
| 6 | Output 6 | Input 6 |
| 7 | Output 7 | Input 7 |
| 8 | Output 8 | Input 8 |
| 9 | Output 9 | Input 9 |
| 10 | Output 10 | Input 10 |
| 11 | Output 11 | Input 11 |
| 12 | Output 12 | Input 12 |
| 13 | Output 13 | Input 13 |
| 14 | Output 14 | Input 14 |
| 15 | Output 15 | Input 15 |
| 16 | Output 16 | Input 16 |
| Mating Connector | | |

| Vcc Connector | |
|------------------|------------|
| Pin Number | Assignment |
| 1 | Vcc 1-4 |
| 2 | Vcc 5-8 |
| 3 | Vcc 9-12 |
| 4 | Vcc 13-16 |
| 5 | Vcc 17-20 |
| 6 | Vcc 21-24 |
| 7 | Vcc 25-28* |
| 8 | Vcc 29-32* |
| 9 | Common |
| Mating Connector | |

*N/A on 24 In/24 Out

| Pin Number | Upper Connector | Lower Connector |
|------------------|-----------------|-----------------|
| | Assignment | Assignment |
| 1 | Output 17 | Input 17 |
| 2 | Output 18 | Input 18 |
| 3 | Output 19 | Input 19 |
| 4 | Output 20 | Input 20 |
| 5 | Output 21 | Input 21 |
| 6 | Output 22 | Input 22 |
| 7 | Output 23 | Input 23 |
| 8 | Output 24 | Input 24 |
| 9 | Output 25* | Input 25* |
| 10 | Output 26* | Input 26* |
| 11 | Output 27* | Input 27* |
| 12 | Output 28* | Input 28* |
| 13 | Output 29* | Input 29* |
| 14 | Output 30* | Input 30* |
| 15 | Output 31* | Input 31* |
| 16 | Output 32* | Input 32* |
| Mating Connector | | |

*N/A on 24 In/24 Out

D.1



WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.

Figure 38. 32 In/32 Out or 24 In/24 Out A-60150-x

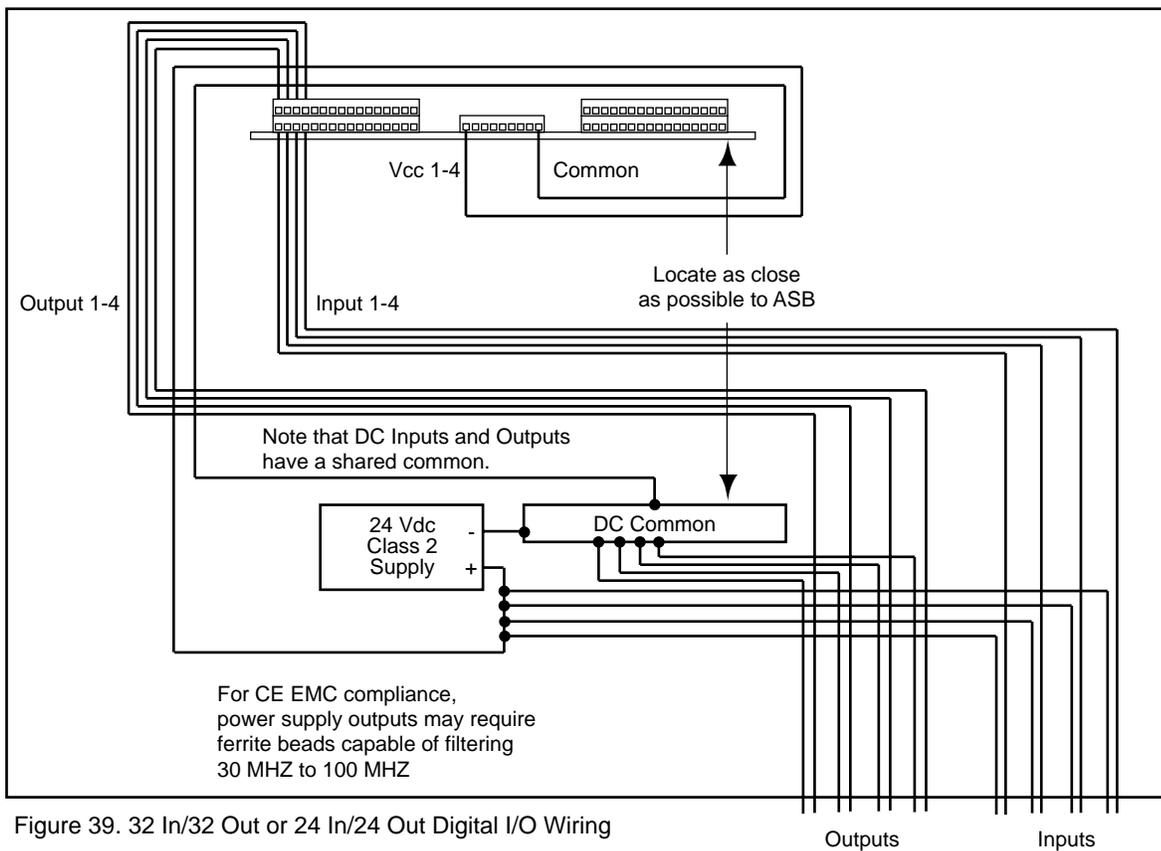


Figure 39. 32 In/32 Out or 24 In/24 Out Digital I/O Wiring

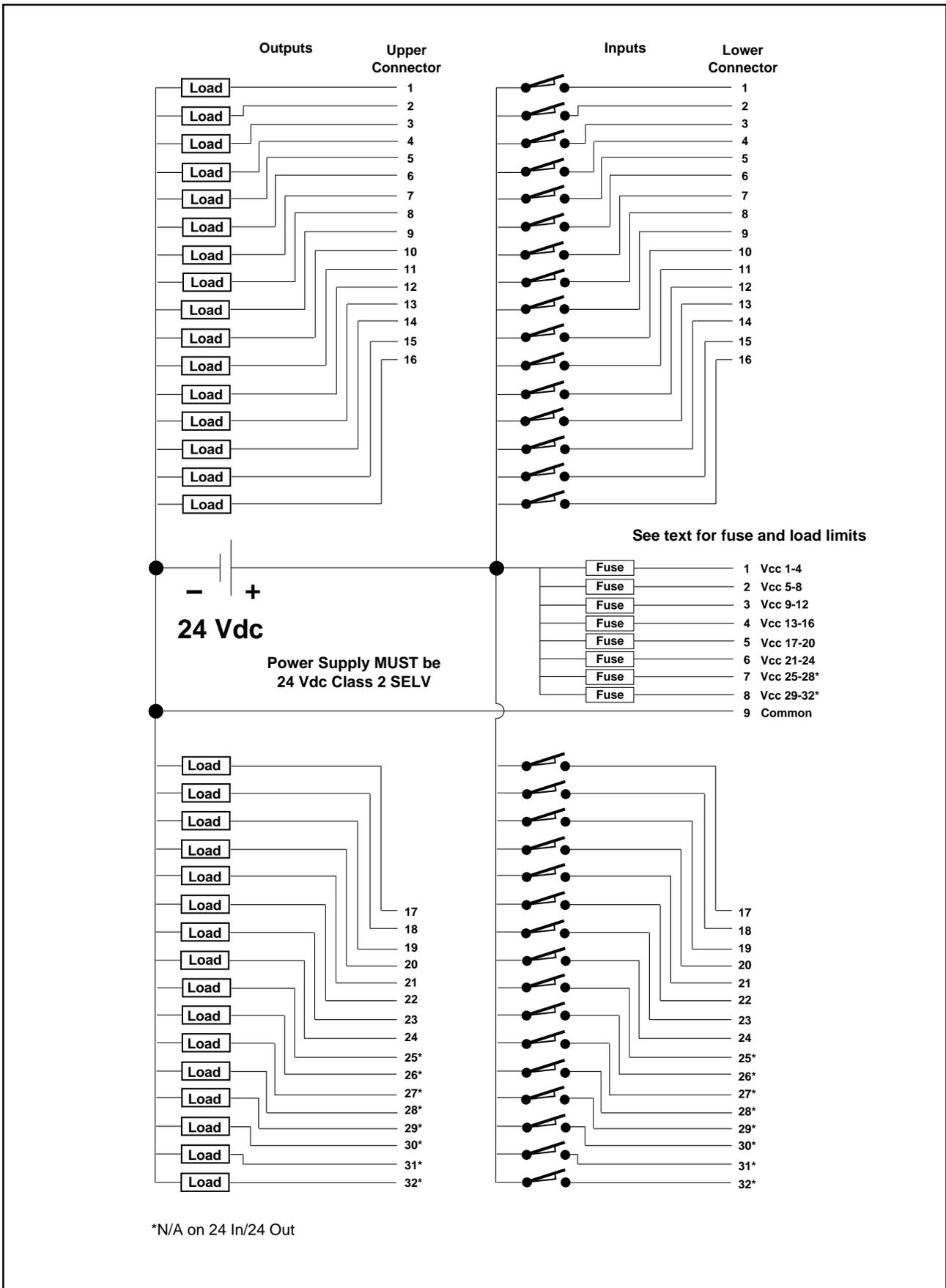
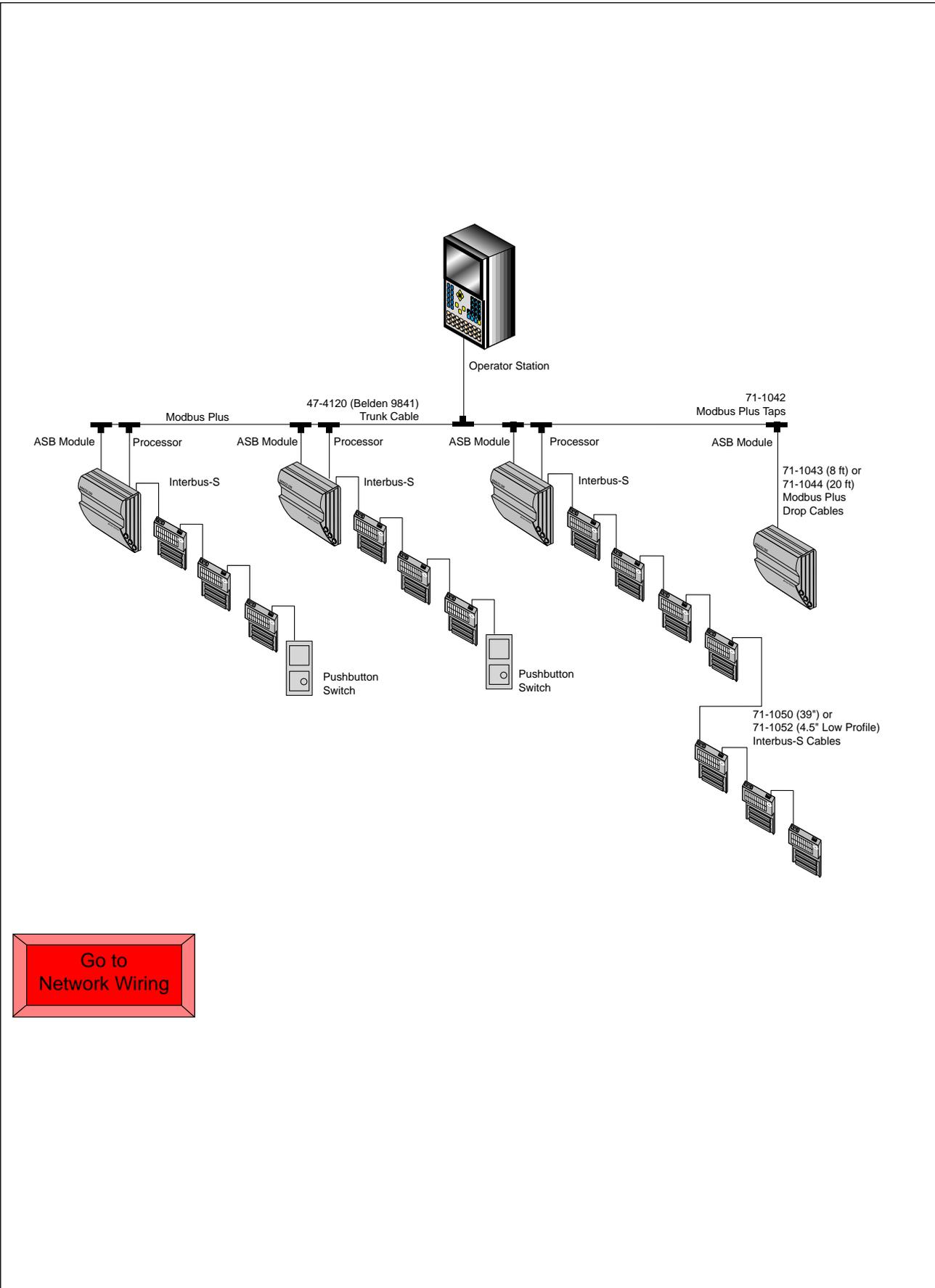


Figure 40. 32 In/32 Out or 24 In/24 Out Sample Wiring



Go to
Network Wiring

Figure 41. Sample System Wiring

D.1

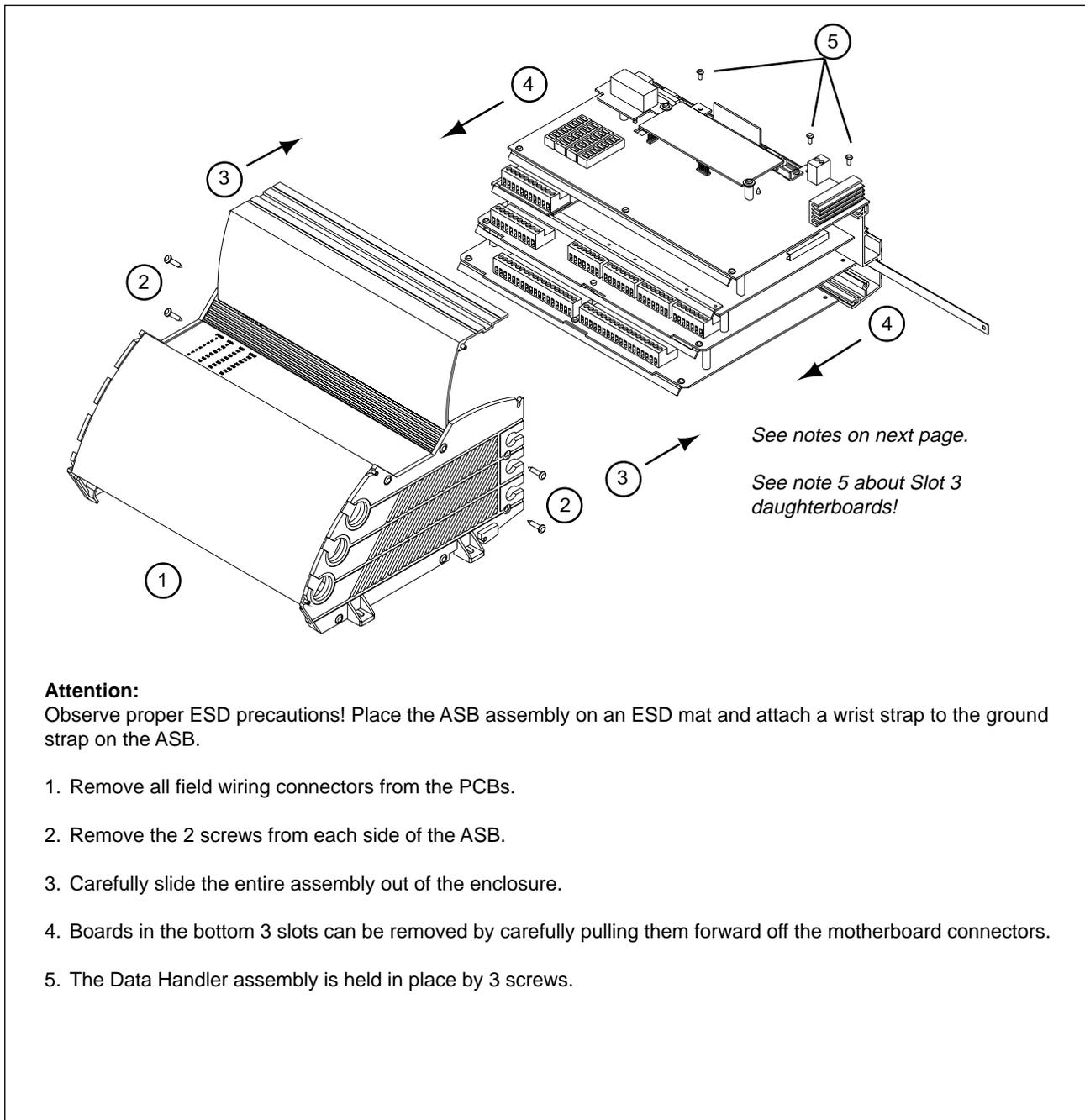


WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.



Attention:

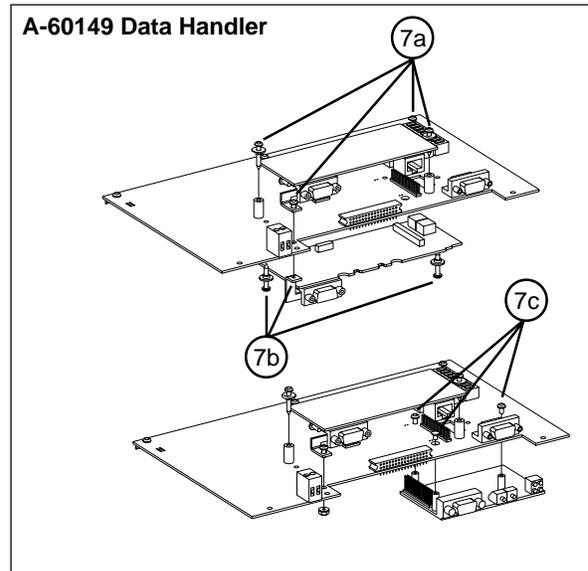
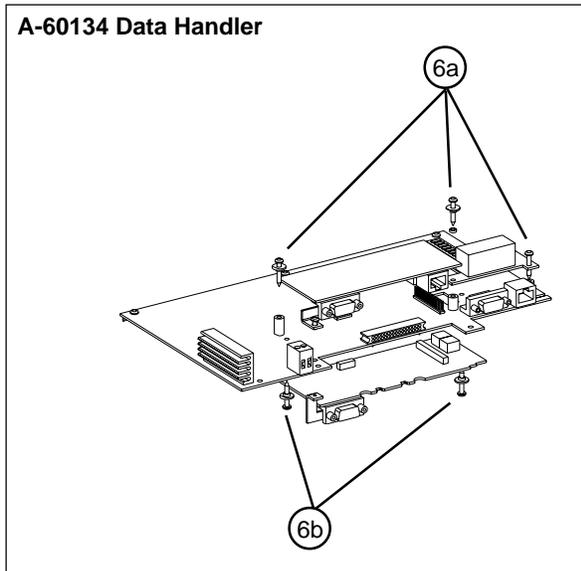
Observe proper ESD precautions! Place the ASB assembly on an ESD mat and attach a wrist strap to the ground strap on the ASB.

1. Remove all field wiring connectors from the PCBs.
2. Remove the 2 screws from each side of the ASB.
3. Carefully slide the entire assembly out of the enclosure.
4. Boards in the bottom 3 slots can be removed by carefully pulling them forward off the motherboard connectors.
5. The Data Handler assembly is held in place by 3 screws.

Figure 42. Adding or Replacing Boards

6. On the A-60134 data handler, the communications board and battery are held in place by 3 screws and the processor board is held in place by 2 screws.

7. On the A-60149 data handler, the communications board is held in place by 4 screws and the processor board (if present) is held in place by 2 screws and a threaded bracket. The Anybus board (if present) is held in place by 3 screws.



NOTES:

1. Slot 1 **MUST** be filled before Slot 2.
2. If a t/c-analog board is used, it must be inserted before a parison, EZ PRO or injection board.
3. If a parison board is used, it must be inserted before an EZ PRO or injection board.
4. If an EZ PRO board is used, it must be inserted before an injection board.
5. Slot 3 is used for I/O boards **ONLY** (Input or Input/Output). Slot 3 daughterboards can be removed **WITHOUT** disassembling the ASB (remove the single screw holding the daughterboard in place and carefully pull forward off the connector).
6. Slot 4 is used for the data handler board **ONLY**.

D.1

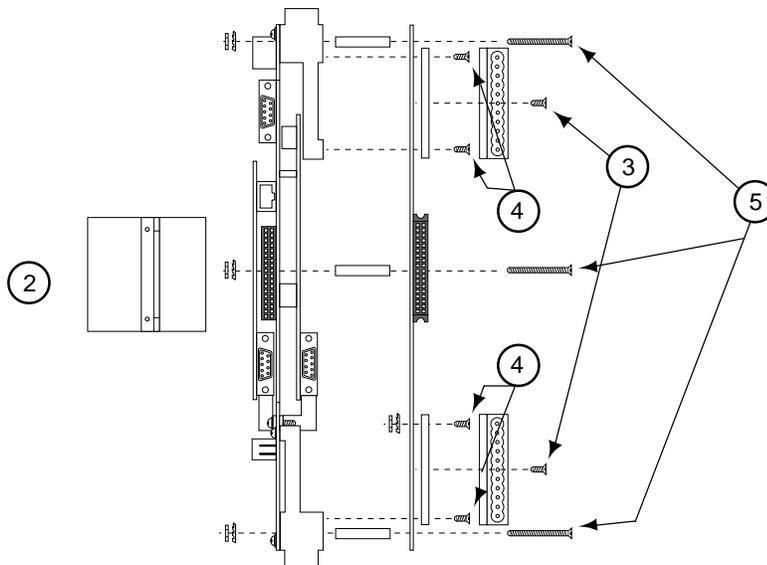


WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE:

Class 2 Wiring must be separated a minimum of 1/4 inch from any Class 1 conductors.



Attention:

Observe proper ESD precautions! Place the data handler block assembly on an ESD mat and attach a wrist strap to the assembly.

1. Remove all field wiring connectors from the PCBs.
2. Remove the "connector board" from the front of the assembly.
3. Remove any daughterboards from the carrier board (remove the single screw holding the daughterboard in place and carefully pull forward off the connector).
4. Remove the screws holding the front of the carrier board in place.
5. Remove the screws holding the rear of the carrier board in place.
6. Refer to the previous pages for disassembling the data handler board.

Figure 43. Disassembling the Data Handler Block

CAUTIONS & WARNINGS NOTICE



IMPORTANT INFORMATION:

Although this instruction manual is written in english, items that are considered to be safety related are marked both with the symbol shown in the margin and an identifying number. In order to locate a message in a specific language, simply note the number and go to that number in the list of messages for that language.



INFORMATION IMPORTANTE

Bien que ce manuel d' instruction soit écrit en Anglais, les points considérés en rapport avec la sécurité sont repérés par le symbole situé dans la marge ainsi qu'un numéro d' identification. Pour localiser un message dans une langue spécifique, simplement noter ce numéro et se reporter à ce numéro dans la liste des messages pour le langage considéré.



INFORMAZIONI IMPORTANTI:

Per quanto questo manuale è stato scritto in inglese, gli articoli considerati importanti per la sicurezza sono marcati sia con il simbolo esposto nel margine sia col numero di identificazione. Per poter trovare un messaggio nella lingua specifica, basta notare il numero ed andare a quel numero nell'elenco di messaggi per quella lingua.



WICHTIGE INFORMATIONEN:

Diese Anleitung wurde zwar in Englisch geschrieben; die Punkte, die sich auf Sicherheitsthemen beziehen, sind jedoch mit dem im Rand gezeigten Symbol sowie einer Kennnummer markiert. Wenn Sie eine Meldung in einer bestimmen Sprache suchen, notieren Sie sich einfach die Nummer und rufen Sie diese Nummer in der Liste mit Meldungen in dieser Sprache auf.



INFORMACIÓN IMPORTANTE:

Aunque el original de este manual de instrucciones está escrito en inglés, los temas que se consideran relacionados con la seguridad están marcados con el símbolo que aparece en el margen y con un número de identificación. Para localizar un mensaje en determinado idioma basta anotar el número y buscar ese número en la lista de mensajes correspondientes a ese idioma.

CAUTIONS & WARNINGS NOTICE

A.1



CAUTION:

Risk of Electric Shock - More than one disconnect switch may be required to deenergize the equipment before servicing.

B.1



CAUTION:

Do Not Operate Without Cover in Place. Cover must be in place both for operator safety and to insure proper cooling of internal components.

C.1



WARNING:

Use of improper battery could present a risk of fire or explosion of the battery.

D.1



WARNING:

Hazardous extraneous voltage capable of causing severe injury or death may exist between sensor leads and ground. Disconnecting the instrument power may not remove this voltage. Measure for the presence of voltage between each sensor lead and ground before servicing. Do NOT place power wiring in the same conduit or wiring trough with sensor wiring.

NOTICE D'AVERTISSEMENTS ET D'ALARMES

- A.1**  **AVERTISSEMENT/ATTENTION:**
Risque de décharge électrique. Il peut être nécessaire de désactiver plus d' un commutateur afin de désamorcer l' équipement avant toute intervention.
- B.1**  **AVERTISSEMENT/ATTENTION:**
Ne pas opérer la machine sans les capots de protection en place. Les capots de protection doivent être en place aussi bien pour la sécurité de l' opérateur que pour assurer un refroidissement correct des composants internes.
- C.1**  **ALARME/DANGER:**
L' utilisation de batteries ou de piles électriques non conformes peut présenter un risque d' explosion ou d' incendie au sein de la batterie ou de la pile.
- D.1**  **ALARME/DANGER:**
Des courants imprévisibles de très haut voltages pouvant occasionner de sévères blessures par électrocution, ou même mort d' homme peuvent exister entre les fils des détecteurs et les prises de terre. Déconnecter l' alimentation des instruments peut ne pas annuler ce voltage existant. Effectuer un contrôle électrique pour confirmer la présence de voltage entre chaque cable des détecteurs et les prises de terre avant toute réparation. Ne PAS mettre les cables d' alimentation dans la même conduite, ou bien les conducteurs en contact avec les fils des détecteurs.

NOTIZIA DI PRECAUZIONI E AVVISI

- A.1**  **PRECAUZIONE:**
Rischio di scossa elettrica - Potrebbe occorrere l'azionamento di più di un interruttore per disattivare l'apparecchiatura prima delle riparazioni.
- B.1**  **PRECAUZIONE:**
Non adoperare senza il coperchio in posizione. Il coperchio deve essere in posizione sia per la sicurezza dell'operatore sia per assicurare il giusto raffreddamento dei componenti interni.
- C.1**  **AVVISO:**
L'uso della batteria sbagliata potrebbe presentare un rischio di incendio o esplosione della batteria stessa.
- D.1**  **AVVISO:**
Ci potrebbe essere un pericolo di voltaggio estraneo fra i fili elettrici e la terra capace di causare un infortunio severo o la morte. Lo stacco dell'energia allo strumento potrebbe non togliere questo voltaggio. Misurare per la presenza di voltaggio fra ogni filo elettrico di sensore e la terra prima di fare servizio. **NON** mettere i fili elettrici nello stesso condotto o canale trasportatore con i fili elettrici di sensore.

ACHTUNGS UND WARNHINWEISE

- A.1**  **ACHTUNG:**
Gefahr von elektrischem Schlag! Vor einer Reparatur kann es notwendig sein, dass mehr als ein Schalter ausgeschaltet werden muss.
- B.1**  **ACHTUNG:**
Nicht ohne eingebaute Abdeckung in Betrieb nehmen. Abdeckung muß aus Sicherheitsgründen für Bediener sowie zur ordnungsgemäßen Kühlung interner Komponenten installiert sein.
- C.1**  **WARNUNG:**
Die Verwendung einer unsachgemäßen Batterie könnte ein Brandrisiko oder Explosionsrisiko für die Batterie darstellen.
- D.1**  **WARNUNG:**
Zwischen Sensorzuleitungen und Masse können gefährliche externe Spannungen anliegen, die zu ernsthaften Verletzungen, eventuell mit Todesfolgen führen können. Durch das Abtrennen der Stromversorgung des Instruments wird die Spannung unter Umständen nicht beseitigt. Zwischen jeder Sensorzuleitung und Masse vor dem Durchführen von Wartungsmaßnahmen eine Messung zur Feststellung eventuell vorhandener Spannung durchführen. Die Stromverdrahtung NICHT im selben Kabelkanal oder Kabeltrog installieren, der für die Sensorverdrahtung verwendet wird.

NOTIFICACION DE PRECAUCIONES Y ADVERTENCIAS

- A.1**  **PRECAUCIÓN:**
Peligro de choque eléctrico - Puede ser necesario desconectar más de un interruptor para cortar la corriente del equipo antes de realizar el servicio.
- B.1**  **PRECAUCIÓN:**
No operar cuando la tapa no esté colocada. La tapa debe estar en su sitio por razones de seguridad del operador y a los efectos de un adecuado enfriamiento de los componentes internos.
- C.1**  **ADVERTENCIA:**
El uso de una batería inadecuada puede presentar riesgo de incendio o explosión de la batería.
- D.1**  **ADVERTENCIA:**
Entre los conductores del sensor y la conexión a tierra puede haber un peligroso voltaje extraño que puede causar graves lesiones, o la muerte. Antes de realizar el servicio, efectúe mediciones para detectar la presencia de voltaje entre cada conductor del sensor y la conexión a tierra. NO instale cableado eléctrico en el mismo conducto o canal de cableado con el cableado del sensor.





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Phone: 703-443-0000

Fax: 703-669-1300

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